Transistor Tester with AVR microcontroller and a little more
Version 1.12k

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<table>
<thead>
<tr>
<th>Section</th>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>5.1.5</td>
<td>Results of different measurements</td>
<td>65</td>
</tr>
<tr>
<td>5.2</td>
<td>Resistor Measurement</td>
<td>69</td>
</tr>
<tr>
<td>5.2.1</td>
<td>Resistor Measurement with 680 Ohm Resistors</td>
<td>69</td>
</tr>
<tr>
<td>5.2.2</td>
<td>Resistor Measurement with 470 kOhm resistors</td>
<td>71</td>
</tr>
<tr>
<td>5.2.3</td>
<td>Results of the resistor measurements</td>
<td>72</td>
</tr>
<tr>
<td>5.3</td>
<td>Measurement of Capacitors</td>
<td>77</td>
</tr>
<tr>
<td>5.3.1</td>
<td>Discharging of Capacitors</td>
<td>77</td>
</tr>
<tr>
<td>5.3.2</td>
<td>Measurement of big Capacitors</td>
<td>77</td>
</tr>
<tr>
<td>5.3.3</td>
<td>Measurement of small Capacitors</td>
<td>80</td>
</tr>
<tr>
<td>5.3.4</td>
<td>Measurement of the Equivalent Series Resistance ESR</td>
<td>82</td>
</tr>
<tr>
<td>5.3.5</td>
<td>Measurement of the Equivalent Series Resistance ESR, first way</td>
<td>84</td>
</tr>
<tr>
<td>5.3.6</td>
<td>Measurement of the Equivalent Series Resistance ESR, second way</td>
<td>87</td>
</tr>
<tr>
<td>5.3.7</td>
<td>Voltage loss after a load pulse, Vloss</td>
<td>93</td>
</tr>
<tr>
<td>5.3.8</td>
<td>Separate capacity and ESR measurement</td>
<td>94</td>
</tr>
<tr>
<td>5.3.9</td>
<td>Results of Capacitor measurement</td>
<td>95</td>
</tr>
<tr>
<td>5.3.10</td>
<td>Automatic calibration of the capacitor measurement</td>
<td>99</td>
</tr>
<tr>
<td>5.4</td>
<td>Measurement of Inductance</td>
<td>103</td>
</tr>
<tr>
<td>5.4.1</td>
<td>Results of the inductance measurements</td>
<td>104</td>
</tr>
<tr>
<td>5.5</td>
<td>Selftest Function</td>
<td>105</td>
</tr>
<tr>
<td>5.5.1</td>
<td>Some Results of the Selftest Function</td>
<td>109</td>
</tr>
<tr>
<td>5.6</td>
<td>Measurement of frequency</td>
<td>112</td>
</tr>
<tr>
<td>6</td>
<td>Signal Generation</td>
<td>114</td>
</tr>
<tr>
<td>6.1</td>
<td>Frequency Generation</td>
<td>114</td>
</tr>
<tr>
<td>6.2</td>
<td>Puls width generation</td>
<td>114</td>
</tr>
<tr>
<td>7</td>
<td>Known errors and unsolved problems</td>
<td>115</td>
</tr>
<tr>
<td>8</td>
<td>Special Software Parts</td>
<td>116</td>
</tr>
<tr>
<td>9</td>
<td>To Do List and new ideas</td>
<td>117</td>
</tr>
</tbody>
</table>
Preface

Basically Motive

Every hobbyist knows the following problem: You disassemble a Transistor out of a printed board or you get one out of a collection box. If you find out the identification number and you already have a data sheet or you can get the documents about this part, everything is well. But if you don’t find any documents, you have no idea, what kind of part this can be. With conventional approach of measurement it is difficult and time-consuming to find out the type of the part and parameters. It could be a NPN, PNP, N- or P-Channel-Mosfet etc. It was the idea of Markus F. to hand over the work to a AVR microcontroller.

As my work has started

My work with the software of the TransistorTester of Markus F. [1] has started, because I had problems with my programmer. I had bought a printed board and components, but I could not program the EEprom of the ATmega8 with the Windows driver without error messages. Therefore I took the software of Markus F. and changed all the accesses from the EEprom memory to flash memory accesses. By analysing the software in order to save memory at other places of program, I had the idea, to change the result of the ReadADC function from ADC units to millivolt (mV) units. The mV resolution is needed for any output of voltage values. If ReadADC returns directly the mV resolution, I can save the conversion for each output value. This mV resolution can be get, if you first accumulate the results of 22 ADC readings. The sum must be multiplied with two and divided by nine. Then we have a maximum value of \( \frac{1023 \times 22 \times 2}{9} = 5001 \), which matches perfect to the wanted mV resolution of measured voltage values. So I additionally had the hope, that the enhancement of ADC resolution by oversampling could help to improve the voltage reading of the ADC, as described in AVR121 [5]. The original version ReadADC has accumulated the result of 20 ADC measurements and divides afterwards by 20, so the result is equal to original ADC resolution. By this way never a enhancement of ADC resolution can take place. So I had to do little work to change the ReadADC, but this forced analysing the whole program and change of all “if-statements” in the program, where voltage values are queried. But this was only the beginning of my work!

More and more ideas to make measurement faster and more accurate has been implemented. Additionally the range of resistor and capacity measurements are extended. The output format for LCD-Display was changed, so symbols are taken for diodes, resistors and capacitors instead of text. For further details take a look to the actual feature list chapter [4]. Planned work and new ideas are accumulated in the To Do List in chapter [9]. By the way, now I can program the EEprom of the ATmega with Linux operating system without errors.

At this place I would like to thank the originator and software author Markus Frejek, who has enabled the continuation with his initial work. In addition I would like to say thanks to the authors of numerous input to the discussion forum, which have assist me, to find new tasks, weak points and errors. Next I would like to thank Markus Reschke, who give me the permission, to publish his cheerful software versions at the SVN server. Furthermore some ideas and software part of Markus R. was integrated in my own software version, again thank you very much. Also Wolfgang SCH. has done a great job to support a graphical display with ST7565 controller. Many thanks to him for integrating his patch for 1.10k software version to the actual developer version. I have to thank also Asco B., who has developed a new printed board, to enable the reproductions for other hobbyists. Another thank I would like to send to Dirk W., who has handled the omnibus order for this printed board. Never I had time enough to handle these things concurrently with my software developement, at no time the state of further developement of software would have the same level. Thanks for the many suggestions to improve the tester to the members of the local chapter of the
"Deutscher Amateur Radio Club (DARC)" in Lennestadt. Last but not least I would say thanks to Nick L. from Ukraine, who has supported my with his prototype boards, has suggested some hardware add ons and also has organized the russian translation for this description.
Chapter 1

Features

1. Operates with ATmega8, ATmega168 or ATmega328 microcontrollers. Additionally ATmega644, ATmega1284, ATmega1280 or ATmega2560 microcontrollers can be used.

2. Displaying the results to a 2x16 or a 4x16 character LCD-Display. If the processor have at least 32K flash memory, also a graphical display with 128x64 pixel and a ST7565, ST7920, ST7108, KS0108 or a SSD1306 controller can be used. In doing so a 4-wire SPI interface or a I²C bus must be used instead of the 4-bit parallel interface for the SSD1306 controller. Even color displays with ILI9163 or ST7735 controller are usable with the SPI interface. For the ST7108 or KS0108 controller you must use a serial - parallel interface with a 74HC(T)164 or a 74HC(T)595. Displays with PCF8812 or PCF8814 controller can be only used without the big icons for transistors, because the display size is unsufficient (102x65 and 96x65).

3. One key operation with automatic power shutdown.

4. Battery operation is possible since shutdown current is only about 20\(\text{nA}\).

5. Low cost version is feasible without crystal and auto power off. With software version 1.05k the sleep modus of the Atmega is used to reduce current if no measurement is required and no rotary encoder is used (not with ATmega8).

6. Automatic detection of NPN and PNP bipolar transistors, N- and P-Channel MOSFETs, JFETs, diodes, double diodes,N- and P-IGBTs, Thyristors and Triacs. For Thyristors and Triacs the ignition current and holding current must be reached with the tester. For IGBTs the 5\(V\) signal should be enough for driving the gate voltage.

7. Automatic detection of pin layout of the detected part.

8. Measuring of current amplification factor and Base-Emitter threshold voltage of bipolar transistors.

9. Darlington transistors can be identified by the threshold voltage and high current amplification factor.

10. Detection of the protection diode of bipolar transistors and MOSFETs.

11. Measuring of the Gate threshold voltage, the Gate capacity value and the R\(\text{DSon}\) at almost 5\(V\) gate voltage of MOSFETs.

12. Up to two Resistors are measured and shown with symbols and values with up to four decimal digits in the right dimension. All symbols are surrounded by the probe numbers of the Tester (1-3). So Potentiometer can also be measured. If the Potentiometer is adjusted to one of its ends, the Tester cannot differ the middle pin and the end pin.
13. Resolution of resistor measurement is now up to 0.01Ω, values up to 50MΩ are detected.

14. One capacitor can be detected and measured. It is shown with symbol \[ \parallel \] and value with up to four decimal digits in the right dimension. The value can be from 25pF (8MHz clock, 50pF @1MHz clock) to 100mF. The resolution can be up to 1pF (@8MHz clock).

15. For capacitors with a capacity value above 90nF the Equivalent Serial Resistance (ESR) is measured with a resolution of 0.01Ω and is shown with two significant decimal digits. This feature is only available for ATmega with at least 16K flash memory.

16. For capacitors with a capacity value above 5000pF the voltage loss after a load pulse can be determined. The voltage loss give a hint for the quality factor of the capacitor.

17. Up to two diodes are shown with symbol \[ \Rightarrow \] or symbol \[ \Rightarrow \] in correct order. Additionally the flux voltages are shown.

18. LED is detected as diode, the flux voltage is much higher than normal. Two-in-one LEDs are also detected as two diodes.

19. Zener-Diodes can be detected, if reverse break down Voltage is below 4.5V. These are shown as two diodes, you can identify this part only by the voltages. The outer probe numbers, which surround the diode symbols, are identical in this case. You can identify the real Anode of the diode only by the one with break down (threshold) Voltage nearby 700mV!

20. If more than 3 diode type parts are detected, the number of founded diodes is shown additionally to the fail message. This can only happen, if Diodes are attached to all three probes and at least one is a Z-Diode. In this case you should only connect two probes and start measurement again, one after the other.

21. Measurement of the capacity value of a single diode in reverse direction. Bipolar Transistors can also be analysed, if you connect the Base and only one of Collector or Emitter. If a ATmega with more than 16K flash memory is used, also the reverse current of the diode is measured with a resolution of 2nA. The value is only output to the screen, if it is greater than zero.

22. Only one measurement is needed to find out the connections of a bridge rectifier.

23. Capacitors with value below 25pF are usually not detectet, but can be measured together with a parallel diode or a parallel capacitor with at least 25pF. In this case you must subtract the capacity value of the parallel connected part. For processors with at least 32K flash memory the tester changeover to a special capacity meter function, if a capacitor with more than 25pF is once measured at TP1 and TP3. In this capacitor meter mode you can measure capacitors below 25pF at TP1 and TP3 directly.

24. For resistors below 2100Ω also the measurement of inductance will be done, if your ATmega has at least 16K flash memory. For that a inductor icon \[ \Rightarrow \] is shown behind the resistor icon \[ \Rightarrow \]. The range will be from about 0.01mH to more than 20H, but the accuracy is not good. The measurement result is only shown with a single component connected.

25. Testing time is about two seconds, only capacity or inductance measurement can cause longer period.

26. Software can be configured to enable series of measurements before power will be shut down.

27. Build in selftest function with optional 50Hz Frequency generator to check the accuracy of clock frequency and wait calls (only for processors with at least 32K flash memory).
28. Selectable facility to calibrate the internal port resistance of port output and the zero offset of capacity measurement with the selftest (only for processors with at least 16K flash memory). A external capacitor with a value between 100nF and 20µF connected to pin 1 and pin 3 is necessary to compensate the offset voltage of the analog comparator. This can reduce measurement errors of capacitors of up to 40µF. With the same capacitor a correction voltage to the internal reference voltage is found to adjust the gain for ADC measuring with the internal reference.

29. Display the Collector cutoff current $I_{C_E0}$ with currentless base (1µA units) and Collector residual current $I_{CES}$ with base hold to emitter level (only for processors with at least 16K flash). This values are only shown, if they are not zero (especially for Germanium transistors).

30. For a ATmega with at least 32K flash memory the tester changes the operation modus from universal tester to a resistor tester, if only one resistor is detected at the test pin 1 (TP1) and test pin 3 (TP3). If you have selected the additional measurement of inductance for the resistor meter function with the Makefile option RMETER_WITH_L, also the inductance of components is measured in this mode. This special operating mode is indicated with a [R] or [RL] at the right side of the first display line. In the same way the tester changes to a capacity meter function, if a capacitor is detected at TP1 and TP3. This operation mode is indicated with a [C] at the right side of the first display line. With this capacity meter function capacity values are shown down to 1pF. Only for the automatic start you need a capacitor with more than 25pF. Both special modes can be finished by a key press. The tester will then continue with the normal tester function.

31. For processors with at least 32K flash a dialog function can be selected, which enable additional functions. Of course you can return from dialog to the normal Transistor Tester function.

32. With dialog function you can use a frequency measurement at port PD4 of the ATmega. The resolution is 1Hz for input frequencies above 25kHz. For lower frequencies the resolution can be up to 0.001mHz by measuring the mean period. You should read the the subsection Frequency measurement 2.2.4 at page 12 for details of connection a frequency signal.

33. With the dialog function and without the activated serial output a external voltage of up to 50V can be measured with the 10:1 voltage divider at the PC3 port. If the PLCC-Version of the ATmega328 is used, one of the additional pins can be used for the voltage measurement together with the serial output. If the zener diode measurement extension (DC-DC converter) is assembled, the measurement of zener diodes is also possible with this function by pressing the key.

34. With the dialog function a frequency output can be selected at the TP2 pin (PB2 Port of the ATmega). Currently a preselection of frequencies from 1Hz up to 2MHz can be selected.

35. With the dialog function a fixed frequency output with selectable pulse width can be activated at the TP2 pin (PB2 port of the ATmega). The width can be enhanced with 1% by a short key press or with 10% by a longer key press.

36. With the dialog function can be started a separated capacity measurement with ESR measurement. Capacities from about 2µF up to 50mF can most be measured in circuit, because only a little measurement voltage of about 300mV is used. You should make shure, that all capacitors have no residual charge before starting any measurement, especially if you use the tester for measurement of capacitor in circuit.
Thyristors and Triacs can only be detected, if the test current is above the holding current. Some Thyristors and Triacs need as higher gate trigger current, than this Tester can deliver. The available testing current is only about 6mA! Also a IGBT can only be detected correctly, if a voltage of 5V is sufficient to drive the gate. Notice that many features can only be used with microcontroller with enough program memory such as ATmega168. Only processors with at least 32k flash memory like ATmega328 or ATmega1284 can take all features.

Attention: Always be sure to discharge capacitors before connecting them to the Tester! The Tester may be damaged before you have switched it on. There is only a little protection at the ATmega ports.

Extra causion is required if you try to test components mounted in a circuit. In either case the equipment should be disconnected from power source and you should be shure, that no residual voltage remains in the equipment.
Chapter 2

Hardware

2.1 Circuit of the Transistor Tester

The circuit of the Transistor Tester in figure 2.1 is based on the circuit of Markus F. released in Abb. 1 of AVR-Transistortester report [1]. Changed or moved parts are marked with green color, optional parts are marked with red color.

Some changes are made because the electronical power switch make problems in some implementations. Therefore the resistor R7 is reduced to 3.3\(\Omega\). The capacitor C2 is reduced to 10 nF and R8 is moved so that the PD6 output does not try to switch the C2 capacitor directly. Additional blocking capacitors are added and should be placed near the power connection of the Atmega and near the Voltage regulator.

Because the PD7 input and PC6 (RESET) are the only pins, where pull up resistors where needed, one extra 27\(k\Omega\) resistor is added to the PD7 (pin 13) input. With this modification the software can disable all internal pull up resistors of the ATmega.

The additional crystal with its 22\(pF\) capacitors are optional added. The accuracy of a crystal has the benefit of more stable time measurement for getting the capacitor values.

New software version can use a voltage scale switch of the ADC. The speed of switching is reduced by the external capacitor C1 at the AREF (21) pin of the ATmega. To avoid slowing down the measurement speed more than necessary, the value of this capacitor should be reduced to 1nF. Removing of the capacitor C1 is also possible. For adapting the software to the actual circuit take a look to the Makefile options in the configuring chapter 4 at page 44.

Some different versions of R11 / R12 resistor combinations circulates in the internet. I have adapted my software to the original of Markus F. [1] with 10\(k\Omega\) and 3.3\(k\Omega\). The voltage ration of the divider can be set with Makefile options.

The additional 2.5\(V\) precision voltage reference connected at pin PC4 (ADC4) can be used to check and calibrate the VCC voltage, but is not required. You can use a LM4040-AIZ2.5 (0.1%), a LT1004CZ-2.5 (0.8%) or a LM336-Z2.5 (0.8%) as voltage reference. If you don’t install the precision voltage reference and you don’t add the relay extension, you should install a pull up resistor R16 to PC4 with a higher resistance value (47\(k\Omega\)). This helps the software to detect the missing voltage reference. A optional ISP connector has been added to easier load new software versions to the tester.
Figure 2.1. New circuit of Transistor Tester

The table 2.1 shows the assignment of the port D for different display versions and the assignment of the additional functions. For the SPI interface a signal LCD-CE is available at the ATmega port. The controller input CE (Chip Enable) can be also connected to GND instead of connecting this input to the ATmega output LCD-CE.

<table>
<thead>
<tr>
<th>Port</th>
<th>Character LCD</th>
<th>ST7565 LCD SPI</th>
<th>ST7920 LCD serial</th>
<th>ST7108 LCD serial</th>
<th>SSD1306 I²C</th>
<th>additional function</th>
</tr>
</thead>
<tbody>
<tr>
<td>PD0</td>
<td>LCD-D4</td>
<td>LCD-REST</td>
<td>LCD-REST</td>
<td>595-PCLK</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PD1</td>
<td>LCD-D5</td>
<td>LCD-RS</td>
<td>LCD-RS</td>
<td>LCD-CS2</td>
<td>LCD-SDA</td>
<td>rotary encoder 2</td>
</tr>
<tr>
<td>PD2</td>
<td>LCD-D6</td>
<td>LCD-SCLK</td>
<td>LCD-B0</td>
<td>164-595-CLK</td>
<td>LCD-SDA</td>
<td></td>
</tr>
<tr>
<td>PD3</td>
<td>LCD-D7</td>
<td>LCD-SI</td>
<td>LCD-CS1</td>
<td></td>
<td></td>
<td>rotary encoder 1</td>
</tr>
<tr>
<td>PD4</td>
<td>LCD-RS</td>
<td>LCD-RS</td>
<td>LCD-RS</td>
<td>164-595-SER</td>
<td></td>
<td>frequency counter</td>
</tr>
<tr>
<td>PD5</td>
<td>LCD-E</td>
<td>(LCD-CE)</td>
<td>LCD-EN</td>
<td>LCD-EN</td>
<td>LCD-SCL</td>
<td></td>
</tr>
<tr>
<td>PD7</td>
<td>pushbutton</td>
<td>pushbutton</td>
<td>pushbutton</td>
<td>pushbutton</td>
<td>pushbutton</td>
<td></td>
</tr>
</tbody>
</table>

Table 2.1. Pin assignments for different displays

The software can follow to another pin assignment of port D for a simpler connection of the LCD display. The following table 2.2 shows the modifies assignments for the strip grid layout and the alternative connection of a graphical display for the microcontrollers ATmega328. Also the using of port inputs for additional functions is shown. With the connections for the graphical display with the strip grid option (STRIP_GRID_BOARD=1) the frequency counter function can not be used, because the port PD4 (T0) is used. But this connection is used by a chinese version with graphical display. In most cases the additional functions like rotary encoder or frequency counter are easier to build with the board versions for a character display, because the required data signals are routed to the display connector.
Table 2.2. port assignments with option STRIP_GRID_BOARD

2.2 Extensions for the TransistorTester

2.2.1 Protection of the ATmega inputs

For better protection of the ATmega inputs one of the additional circuits can be integrated. The de-energized contacts of the relay protect the ATmega without power. The contacts will be opened by software only for measurement. Also with the additional diode protection the chance of the ATmega will be better to survive the connection of a capacitor with higher residual voltage. A complete protection is not possible. Therefore capacitors should always be discharged before measuring.

![Protection Circuit](image)

Figure 2.2. Additional protection of the ATmega inputs

2.2.2 Measurement of zener voltage above 4 Volt

If the serial output of text is not required, the Pin PC3 of the ATmega can be used as analog input for measuring a external voltage. The voltage can be up to 50V with the optional 10:1 resistor divider and can be used for measuring the breakdown voltage of a zener diode. A current limiting power supply with up to 50V can be switched on with low signal at PD7 pin of the ATmega to deliver current for testing the break down voltage of a zener diode. Figure shows a suggestion for this expansion. The tester shows the external voltage as long as you hold the key pressed. About 40mA more battery current is used by this expansion during key pressing.
The 10:1 voltage divider can be used with the optional dialog part for the ATmega328 without the activated DC-DC converter for the zener diode measurement. Without the pressed key the voltage converter is not powered. For that the external voltage (for example battery voltage) can be measured at the zener diode port. You can only measure positive DC voltages up to 50V. You have also to respect the correct polarity.

2.2.3 Frequency generator

With the dialog part of the ATmega you can also select a frequency generator, which supports currently a selection of frequencies from 1 Hz up to 2 MHz. The output of the 5V signal is done with a 680Ω resistor to test port TP2. You can use the GND signal from the minus pin of the zener diode extension or the test port TP1. The test port TP3 is connected to GND with a 680Ω resistor. Of course you can also connect a driver circuit to the ATmega port PB2 with a separate output driver circuit and an additional output terminal. But the input of this circuit should not insert a big capacity load for the ATmega output.

2.2.4 Frequency measurement

For using the with the dialog selectable frequency measurement is a little hardware extension necessary. The input pin PD4 (T0/PCINT20) of the ATmega is used for the frequency measurement. The same pin is also used for the connection of the LCD. With normal layout, the PD4 pin is connected to the LCD-RS signal, with the strip grid design it is connected to LCD-D4. For both signals the PD4 pin can be switched to input as long as no output to the LCD is required. The LCD respect the input value only, if the LCD-E signal is switched to GND. For driving the input pin from external clock source at least one serial resistor of 270Ω should be used. Better you should use the circuit of figure 2.4. The voltage at the PD4 pin (LCD-RS or LCD-D4) should be adjusted to 2.4V without the assembled ATmega or during frequency measurement of the ATmega, to get the best sensitivity for the input frequency signal. The LCD should always be installed for adjusting, because the pull up resistor of the LCD change the voltage.
2.2.5 Using of a rotary pulse encoder

For easier control of the menu function for the ATmega328 you can expand the circuit by a rotary pulse encoder with a push button. The circuit 2.5 shows a standard expansion for a normal character LCD. All signals for the connection of the rotary pulse encoder are available at the plug connector for the LCD. For this reason the expansion can also be easy upgraded for many existing testers. In many cases the graphical LCD is assembled on a adapter board with some connection pins of the character LCD. Also in this cases the upgrade with a rotary encoder is not very difficult to do.

The figure 2.6 shows the feature of two different rotary pulse encoder. The version 1 has twice as much indexed positions (detents) per turn as pulses per turn. The version 2 has the same count of detents as pulses per turn. The slope of one of the two switch signals is sometimes exactly at the detent of the rotary pulse encoder.
The figure 2.7 shows a rotary pulse encoder, which has not only bouncing contacts, but also has a unstable state of one of the switches at the indexed position (detent). Every change of the state of the switches is detected by the program and saved in a cyclic buffer. Therefore the last three states of the switches can be checked after every status change. For every cycle of switch states a total of four sequences of state can be defined for every direction of rotation. If there is only one indexed position (detent) for every cycle of switch states, only one of the state sequence pair must be monitored (WITH_ROTARY_SWITCH=2 or 3) for correct counting. If there are two indexed positions for every cycle of the switch states, as shown in figure 2.7, you must monitor two pairs of switch state sequences (WITH_ROTARY SWITCH=1). You can chose any resolution for the WITH_ROTARY SWITCH for a rotary pulse encoder without indexed positions. A value of 2 or 3 selects the lowest resolution, 1 selects a middle resolution and 5 selects the highest resolution. A oscillation of the selection (counter up, counter down) can be avoided with the type of monitoring, but sometimes a count can be missed with a bad placement of the indexed position.
In place of the two switches of a rotary switch encoder you can also install two separate key buttons for Up and Down movement, if no rotation switch encoder is present or favored. In this case the option WITH_ROTARY_SWITCH must be set to 4 for a correct handling of the program.

### 2.2.6 Connection of a graphical display

Many thanks to Wolfgang Sch. for his work to support a Chinese version with ST7565 controller. By now you can also connect a graphical 128x64 pixel LCD with a ST7565 controller. Because the ST7565 controller is connected with a serial interface, only four signal lines are required. Two port D pins of the ATmega can be used otherwise. The ATmega processor should have at least 32k flash memory for the support of a graphical display. The ST7565 controller works with an operating voltage of 3.3V. Therefore a additional 3.3V voltage regulator is required. The data sheet of the ST7565 controller does not allow the direct connection of input pins to 5V signal level. So the extension of figure 2.8 uses an additional 74HC4050 CMOS device for the conversion of the voltage level. You can try to exchange the four 74HC4050 gates with four resistors of about 2.7kΩ. With the voltage drop at the resistors you will prevent the increase of the 3.3V controller power voltage across the diodes of the controller inputs from the 5V ATmega outputs signals. You have to try, if the signal form with the resistors can be accepted from the ST7565 controller inputs. The signal form at the controller inputs will be more similar to the output shape of the ATmega with the 74HC4050 gates in any case.
 Normally the ST7565 or SSD1306 controller is connected with a 4-wire SPI interface. But with the SSD1306 controller you can also use an I\(^2\)C interface with PD2 as SDA and PD5 as SCL signal. The SDA and SCL signals must be equipped with pull-up resistors of about 4.7\(\Omega\) to 3.3\(V\). A solution for connecting the OLED display shows the figure 2.9. The outputs of the ATmega is only switched to 0\(V\) for the I\(^2\)C signals. Before connecting the pull-up resistors to 5\(V\) you must check, if your display module can tolerate a 5\(V\) signal level. Normally the data inputs of the controller are protected with diodes to 3.3\(V\). You should make shure, that you have loaded a program with the I\(^2\)C support to the ATmega before the Display is connected. If you have loaded a program with another interface, the output are also switched to the 5\(V\) side. Because I have determined a influence to the tester results across the VCC connection of a OLED module, a additional decoupling with a serial resistor of 68\(\Omega\) with a additonal 10\(\mu F\) blocking capacitor is recommended. Instead of the 68\(\Omega\) resistor you can also use a inductor with about 1\(mH\). Without the additional filter my tester has reported collector residual currents with bipolar transistors and a OLED display. Also you should check the pin sequence of your OLED module, some moduls have a different location of GND and VCC.
For connection to the ATmega644 series of processors the pins PB2 to PB5 instead of PD0 to PD3 are used. The exchange of a text display to a graphical display is possible with an adapter printed board because all required data signals and power signals are available at the LCD connector. A little simpler is the connection of a graphical display with a ST7920 controller because the controller can operate with 5V power voltage. For that the display should offer 128x64 visible pixels. The display module with the ST7920 controller can be connected with the 4-bit parallel interface or with a special serial interface, as shown in figure 2.10.

For both connection types the software must be configured in a special way. The Makefile option "WITH_LCD_ST7565 = 7920" must be set in any case, for the serial connection type you must set also the option "CFLAGS += -DLCD_INTERFACE_MODE=5". The orientation of the presentation can be changed with the options LCD_ST7565_H_FLIP and LCD_ST7565_V_FLIP in the same way as with the other graphical displays.

A special case is the connection of displays with a ST7108 controller. Because these displays can only use the 8-bit parallel interface, you must use a serial to parallel converter. The simplest way seems to be the use of a 74HCT164 or a 74HCT595 chip. A suitable suggestion of a connection circuit shows the figure 2.11.
You must check the pin layout of your LCD module, some moduls have different signal sequence. Some different pin layouts found in data sheets for the ABG128064 series are shown in table 2.3.

<table>
<thead>
<tr>
<th>Signal</th>
<th>128064H</th>
<th>128064G</th>
<th>128064C</th>
<th>128064B</th>
</tr>
</thead>
<tbody>
<tr>
<td>VDD (5V)</td>
<td>1</td>
<td>2</td>
<td>4</td>
<td>2</td>
</tr>
<tr>
<td>VSS (GND)</td>
<td>2</td>
<td>1</td>
<td>3</td>
<td>1</td>
</tr>
<tr>
<td>VO (Drive)</td>
<td>3</td>
<td>3</td>
<td>(5)</td>
<td>3</td>
</tr>
<tr>
<td>DB0-DB3</td>
<td>4-7</td>
<td>7-10</td>
<td>9-12</td>
<td>7-10</td>
</tr>
<tr>
<td>DB4-DB7</td>
<td>8-11</td>
<td>11-14</td>
<td>13-16</td>
<td>11-14</td>
</tr>
<tr>
<td>CS1</td>
<td>12</td>
<td>15</td>
<td>1</td>
<td>15</td>
</tr>
<tr>
<td>CS2</td>
<td>13</td>
<td>16</td>
<td>2</td>
<td>16</td>
</tr>
<tr>
<td>Reset</td>
<td>14</td>
<td>17</td>
<td>-</td>
<td>17</td>
</tr>
<tr>
<td>R/W</td>
<td>15</td>
<td>5</td>
<td>7</td>
<td>5</td>
</tr>
<tr>
<td>RS</td>
<td>16</td>
<td>4</td>
<td>6</td>
<td>4</td>
</tr>
<tr>
<td>E</td>
<td>17</td>
<td>7</td>
<td>8</td>
<td>6</td>
</tr>
<tr>
<td>VEE</td>
<td>18</td>
<td>18</td>
<td>-</td>
<td>18</td>
</tr>
<tr>
<td>LEDA</td>
<td>19</td>
<td>19</td>
<td>17</td>
<td>(19)</td>
</tr>
<tr>
<td>LEDK</td>
<td>20</td>
<td>20</td>
<td>18</td>
<td>-</td>
</tr>
</tbody>
</table>

Table 2.3. Pin layout of different ST7108 moduls

You can also use a display with a PCF8814 controller, which is usualy used in a Nokia 1100 handy for example. You must check, which interface of the controller is used in your display module. The PCF8814 controller can support the SPI-interface with 3 lines and 4 lines, the I2C-interface and a special 3-line interface, which receice the data/instruction signal as first serial bit before the 8 data bits. Because the display support only 96x65 pixels, the big icons for transistors are not used with this controller. The output is simular to the character display. As with the most graphical displays this controller also operated with 3.3 Volt. Therefore a signal conversion for the 5V outputs of the ATmega is required. For the SPI interface and the 3-line interface you can use the outputs of the ATmega like "open collector" outputs with the Makefile option LCD_SPI_OPEN_COL. You must use "Pull-Up" resistors with this option or you should not set the option PULLUP_DISABLE in the Makefile. Currently only the 3-line interface is tested with the PCF8814 controller.
Some code for supporting a PCF8812 controller with 102x65 pixels is also implemented, but not yet tested.

### 2.2.7 Connection of a graphical color display

Some Chinese salesmen offer cheap color display modules with a SPI interface. The picture 2.12 shows the backsides of two supported modules with 128x128 pixel and 128x160 pixel. The modules are very small, so the shown text and symbols are very little. But the appearance is sharp and clear.

![Color-LCD's](image)

Figure 2.12. Back side of two Color-LCD’s

The 128x128 pixel modul uses a ILI9163 controller. The 128x160 pixel modul uses a very simular ST7735 controller. The modules are tested with a adapter board, which connects the SPI signals and the power to the terminal for the normal character display. The adaption of the 5V output signals of the ATmega to the 3.3V inputs of the controller is ensured with serial 10kΩ resistors. The background light (LED) is required for this modules because nothing is readable without it. Because of the high count of pixels in vertical direction you can display more text lines for this modules. For the 128x128 pixel display you can display 8 lines of text with a 12x8 font, for the 128x160 pixel display...
you can even show 10 lines of text. At the picture 2.13 you can see the result of the measurement of a Germanium transistor at a 128x128 pixel display.

Figure 2.13. Measurement of a bipolar PNP transistors

The color feature of the modules is currently not used. Simply the background color and the foreground color can be changed in the file lcd_defines.h or in the Makefile. The 16-bit color model of the controller is used by the software, the foreground color can be changed with the constant LCD_FG_COLOR and the background color with the constant LCD_BG_COLOR.

2.3 Hints for building the TransistorTester

Every LCD-display with at least 2x16 character and a HD44780 compatible controller can be used with the TransistorTester. You should respect the current needed for illumination, some LCD need lower current than others. I had tried OLED type displays, but this type cause interference with measurements of the ATmega and are not recommended. Also loading of special characters for displaying the resistor symbol has caused problems with the OLED.

The resistors R1 to R6 are critical for measurements and this 680Ω and 470kΩ resistors should be measurement type resistors (tolerance of 0.1%) to get the full accuracy. You should use a precision socket for the ATmega microcontroller to enable the replacement of the microcontroller. The microcontroller ATmega8, ATmega168 and ATmega328 can be used. Recommended is a ATmega328, if you wish to use all features.

Anyway you should assemble all parts to printed board without the microcontroller. A up-to-date low voltage drop regulator like MCP1702-5002 is recommended as IC2, because it need only 2μA of standby current and can still deliver 5V, if your input voltage is only 5.4V. But this part is not pin compatible to well known 78L05 with TO92 body!

After checking, that all needed parts are at the correct place, you should first connect the battery or power supply to the printed board without LCD-display and microcontroller. You should check the voltage at the power pins of the microcontroller and LCD-display terminal during the Test key is pressed. The voltage should disappear, if you release the Test key. If the voltage had correct polarity and value, you should disconnect the power and assemble the microcontroller with correct alignment. Be careful and make shure, that all pins of the microcontroller are in the socket holes. Now you can
also connect the LCD. Check if power pins of the LCD has the right connection to GND and VCC of your board.

If you are sure that everything is all right, reconnect the power. If you have already programmed the ATmega, you can press the Test button. By pressing the Test key, the background light of the LCD should switch on. If you release the Test button, the LED should illuminate weak. Notice, that the software for the microcontroller must be compiled for the correct processor type. A program for the ATmega8 does not run on a ATmega168!

2.4 Changeover for tester versions designed by Markus F.

Voltage control If the problem exist, the tester will shut down immediately with every switch on. With my suggested setting of the fuses (Makefile) the voltage control of the different ATmega versions is switched to 4V (brown out level). This may be the reason why the tester makes trouble with the power on sequence. The Pin PD6 tries to switch the 100nF capacitor C2 to VCC level causing a voltage breakdown of the VCC voltage (5V). The capacitor C2 can be reduced to < 10nF without problems. If possible, the direct connection of PD6 should be replaced by a resistor > 220Ω.

Improvement of power on circuit Often this problem is the reason, if the tester starts with the button hold pressed, but switch off directly by releasing. The problem is enforced by a high current background light for the LCD. The resistor R7 to the base of the PNP transistor T3 was optimized with the value 27kΩ too much to save power consuming. To improve the switching with lower battery voltage or lower current amplification factor of the PNP transistor T3, you should reduce the resistance to 3kΩ.

Additional pull-up resistor at PD7 The missing pull-up resistor results to a switch off of the tester with the message "Timeout" after a short display time. The software is configured with the option PULLUPDISABLE, that all internal pull-up resistors are switched off. For that reason the voltage of pin PD7 is not defined, if the level is not switched by the push button or transistor T2 to GND. One external pull-up resistor of 27kΩ to VCC avoid this error.

Capacitor C1 at the AREF pin Many designs use a 100nF capacitor at the AREF pin, like the design of Markus F. too. As long as the reference voltage of the ADC is never changed, this is a good solution. The software of the TransistorTester for the ATmega168/328 uses a automatic selection of the internal 1.1V reference voltage of the ADC, if the input voltage is below 1V. With this solution a better resolution of the ADC can be reached for little input voltages. Unfortunately the switching from 5V to 1.1V reference is very slowly. A additional wait time of 10ms must be respected for this reason. With changing the capacity value to 1nF this wait time can be reduced significant. I have not noticed any degradation of measurement quality with this change. Even a removing of the capacitor has no significant change of measurement results. If you prefer to leave the capacitor unchanged, you can remove the option NO_AREF_CAP in the Makefile to activate longer wait times in the program.

Expanding of a 8MHz crystal With some skill you can expand a 8MHz crystal to the backside of the printed board directly to the pins PB6 and PB7 (pin 9 and pin 10). My own expansion was done without the both 22pF capacitors. This solution has operated well with all tested ATmega. But it is not required to use a crystal. You can still use the 8MHz RC oscillater by setting the fuses to get the better resolution of time constant for measuring the capacity values.

Smoothing of the operating voltage The original circuit of Markus F. shows only one 100nF capacitor to block the VCC voltage. This is clearly too little smoothing. You should at least
use one $100\,nF$ near the ATmega power pins and one near the voltage regulator. The input of the voltage regulator should be blocked with a $100\,nF$ too. Additional $10\,\mu F$ capacitors (electrolytic or ceramic) at the input and output of the voltage regulator can stabilise the voltage level. Ceramic $10\,\mu F$ capacitors with SMD mounting form are easier to use for backfitting and have usually a lower ESR value.

**Selection of the ATmega processor** The using of the base function of the tester is still possible with a ATmega8. The flash memory of that device is used near 100%. Because the ATmega168 or ATmeg328 processors are pin-compatible to the ATmega8, I can recommend the replacement. Actually the price for ATmega328 is so cheap, that there is no reason to take a ATmega168 type. With a ATmega168/328 you get the following advantages: Self test with automatic calibration.

- Improvement of measurement quality by automatic switching of ADC scale.
- Measurement of inductors with resistance below $2\,100\Omega$.
- Measurement of ESR value of capacitors with value of above $90\,nF$.
- The resolution of resistor measurement below $10\Omega$ is $0.01\Omega$.
- Using of pin PC4 as serial output.

**Missing precision voltage reference** Usually the software should detect the missing voltage reference with the unconnected pin PC4. In this case no VCC=$x.xV$ message should appear in row 2 of the LCD on power on. If this message appear without the reference, you should connect a $2.2\,k\Omega$ resistor to the PC4 input and VCC.

### 2.5 Chinese clones with text display

As I know, the tester is rebuild in China in two versions with character displays. The first model is rebuild from the first design of Markus F. without the ISP port. The assembled ATmega8 is placed in a socket, so you can replace it with a ATmega168 or ATmega328. For this version you should consider all the hints of section 2.4. Additional $100\,nF$ ceramic capacitors should be connected near by the VCC-GND and AVCC-GND pins of the ATmega for better stabilization of the power voltage. Because there is no ISP connector at the board, you must expand the board with a ISP connector or you must plug the ATmega to a external socket for programming. In addition you should notice, that if your ATmega should run with a $8\,MHz$ crystal, your external ISP programmer must have a external clock for programming or a crystal mounted at the socket.

The second version of rebuilded tester is build with SMD components. Also the fix installed ATmega168 is a SMD type with 32TQFP body. Fortunately on the board is a 10-pole ISP connector provided for the programming. I have analysed the board version "2.1 2012/11/06". One error is the assembly of the part "D1", which should be a precision $2.5V$ voltage reference. Assembled is only a zener diode. This part should be removed. You can mount a LM4040AIZ2.5 or LT1004CZ-2.5 precision voltage reference at this place. A missing voltage reference is noticed by the software, so that you must not install the voltage reference. My exemplar was delivered with software version 1.02k. The 10-pole ISP plug was not assembled and I must install a jumper from ISP pin 6 to ISP pin 10. My programmer expect a GND connection at pin 10, but the board has GND level only on pin 4 and pin 6 of the ISP. The label of the ATmega168 was rub away and there was no documentation delivered with the part. The lock fuses of the ATmega were set, so no readout was possible. But I could install the software version 1.05k without any problems. Another user has problems with the same software version 1.05k. This user has the chinese board "2.2 2012/11/26". The software runs only without problems, if a additional $100\,nF$ keramic capacitor was placed between the pin
18-AVCC and 21-GND near by the ATmega. The software 1.05k uses the sleep state of the ATmega for waiting time. For this reason the current alternates often and the voltage regulator is stressed more. Further I have noticed, that the VCC voltage is blocked with a 100\text{nF} ceramic capacitor and with a 220\text{\mu F} electrolytic capacitor nearby the 78L05 voltage regulator. The 9\text{V} supply voltage is blocked with the same capacitors, but not at the input of the regulator but at the emitter of the PNP transistor (parallel with the battery). The printed circuit board track from the ATmega168 to the test port is very thin, so that a resistance of 100m\text{\Omega} could be measured for one path. This will be the reason for measuring a resistance of 0.3\text{\Omega} for two direct connected pins. The ESR measuring can usually consider this by zero compensation. Beginning with version 1.07k the software does respect this offset for measuring resistors below 10\text{\Omega} too.

### 2.6 Chinese clones with graphical display

Newer rebuilds of the tester like a version from Fish8840 use a 128x64 pixel graphical display. This version use a modified circuit for the switch on logic. The figure 2.14 shows a part of the modified circuit.

![Circuit Diagram](image)

Figure 2.14. Part of the circuit from the Fish8840 version

How you can see at the values of resistor R8 and R15, a 2:1 scaling factor for the battery voltage measurement is used instead of the original scaling factor. In addition R15 is direct connected to the battery, what results to a power consumption in the switch off state. The R15 should better be connected to the drain of Q1 or the input of the voltage regulator to prevent this unneeded battery power consumption. A suitable change of the printed board is shown in picture 2.15. A circuit path is cut between R17 and D5 and a new conductive path is inserted between Q1 and R15 with a enameled copper wire.
The scaling factor of the battery voltage must be specified in any case in the Makefile before any attempt can be done to replace the original software (BAT_NUMERATOR=66 for example).

The display module of the Fish8840 tester is equipped with a 3.3V voltage regulator to adapt the operating voltage of the display controller. Because the 3.3V operating voltage can be increased with the 5V signal level of the data signals from the ATmega, a adapter circuit according to the picture 2.16 is recommended. The four data signal lines are equipped with four serial 2.7kΩ resistors at a little breadboard. Longer spacer bolts must be used to mount the display with the adapter board to the printed board of the Fish8840 tester now.

Instead of this modification you can also use a special output mode of the 4 SPI signals of the ATmega with the Makefile option LCD_SPI_OPEN_COL. With this option the outputs are not switched to VCC level, but the internal ”pull-up” resistors are switched on during the output of a high level. If the option PULLUP_DISABLE is set, additionally a external pull-up resistor for the
"Reset" signal (PD0) is required. Because the data signals are never switched to VCC directly, the 3.3V power of the LCD controller can not be elevated. My version of the Fish8840 tester has all signals for connecting a character display routed to the LCD plug connector. Therefore you can prepare the board for connection of a character display, if the female header is completed and the potentiometer for the contrast level is added. However the supply pin 15 for the background light is connected directly to the VCC level. If you install a character display, you should check, that your display module is equipped with a serial resistor for the background LED. Of course you have to adapt the software for different displays. Also the hardware extension are possible with the Fish8840 board.

All attempt to replace the original software is always done at one’s own risk. No guaranty can be given for operational capability of newer software versions. Unfortunately the original state of the chinese software can not be saved because the security bits of the ATmega328 are set. So there is no way to get back to the original state.

A additional version with graphical display is the WEI_M8 printed board, which is shown in picture [2.17]. This build use a LiIon accumulator with AA (mignon) size as power supply, which can be loaded with the micro USB plug. Operating is also possible without the accumulator, only with the USB power.

![Figure 2.17. Picture of the chinese WEI_M8 tester](image)

It is pleasant, that the signal lines of the display are equipped with serial resistors at the adapter board, as you can see in the left picture of [2.18]. Therefore you must not be afraid that the 5V signals of the ATmega can cause a excessive increase of the 3.3V power of the display controller.
With the upgrade to version 1.12k some problems has occurred. If the extended fuse is set to 0x04 (0xfc) as recommended, some measurements has caused a "Brown Out" reset of the processor. This resets are caused by short voltage drops of the VCC power. I have added a additional 4.7\(\mu F\) ceramic capacitor at the input side of the voltage regulator and a 10\(\mu F\) ceramic capacitor at the output side (VCC) of the regulator. Both before and after the upgrade I have noticed, that with bipolar transistors a residual collector current (ICEO or ICEs) of about 1\(\mu A\) was detected with this board. Not until the unknown LDO voltage regulator was replaced with a MCP1702-5002 this effect has disappeared. The figure 2.19 shows the modified board with the slantwise mounted capacitors and the MCP1702 regulator. If you don’t want to modify your board, you must set the extended fuse to 0x07 (0xff) to enable a regular operation. With that setting the voltage drops remain undetected.

A additional chinese version with graphical display is the "LCD-T4" tester with a yellow printed board. I have removed the display for replacing the software with a newer version. At the right
picture of figure 2.20  you can see in the right upper corner the ISP male connector with correct orientation beside the six holes of the board. For programming the ATmega I have not soldered the male connector. I have only plugged it into the holes instead and have fixed it with a finger during the programming. With that procedure the male connector can be easy removed and the display can be mounted again to its origin place. The Chinese software could be replaced with the 1.12k without any noticeable problem. Also the activating of the ”brown-out” monitor by setting the extended fuse has not shown any surprise.

(a) completely  
(b) with removed display

Figure 2.20. Front view of the T4 tester

You can see the upgraded 5mm threaded bolt and the upgraded cables with measurement clips at the pictures of the back side in figure 2.21. Because the data signals for the graphical LCD controller have also no level adaption (5V -> 3.3V), the setting of the option LCD_SPI_OPEN_COL is recommended. Due to the fact, that the board can not be easy upgraded with a ”pull-up” resistor, it make sense to remove the option PULLUP_DISABLE instead. This board is lesser practical for later extensions, a replacement of the display is also difficult to realize.

(a) components side  
(b) with measurement cables

Figure 2.21. Back side of the T4 tester

A addititonal chinese version with graphical display is offered with the name ”GM328”. For
this version the graphical display is connected with a adapter circuit board to the 16-pol female connector. The port PD5 of the ATmega is connected via pin 6 of the female connector to the CE (Chip Enable) input of the graphical controller. The signal CE is also conneted at the adapter board to the 0V power (GND). This will resulte to a short-circuit if the ATmega will switch the PD5 output to 5V. But newer versions of the software also switch the CE signal, even if the signal is not necessary for correct operation. For correct operation of the ”GM328” tester with newer software versions you should cut the connection of the CE signal to pin 6 of the male connector.

2.7 Extented circuit with ATmega644 or ATmega1284

A extended circuit for ATmega644/1284 processors was developed with Nick L. from the Ukraine. The circuit [2.23] enables a additional test of crystals and a extended range for the frequency measurement. Although the basic circuit is very similar to the circuit [2.1] the port assignment is different. A rotary pulse encoder with circuit [2.5] can be connected here at the pins PB5 and PB7 (instead of PD1 and PD3). Both signals and also the power signals VCC and GND are available at the ISP connector, so that the extension can also be connected here.

The 16:1 frequency divider of the 74HC4060 is allways used for frequencies above 2MHz. The frequency divider can also be used for frequencies between 25kHz and 400kHz to upgrade the frequency resolution by using the period measurement. For switching between the operational states (frequency divider and crystal oszillator) the analog switches 74HC4052 are used. The table [2.5] shows the pin assignments for the ATmega324/644/1284 microcontrollers for different display connections. The using of the I2C interface is only possible with the SSD1306 controller. The signals of the I2C interface require a pull-up resistor of 4.7kΩ to 3.3V. The outputs of the ATmega is only switched to 0V for the I2C signals.

<table>
<thead>
<tr>
<th>Port</th>
<th>Character LCD</th>
<th>Graphic LCD</th>
<th>Graphic LCD</th>
<th>additional function</th>
</tr>
</thead>
<tbody>
<tr>
<td>PB2</td>
<td>LCD-RS</td>
<td>SPI 4-wire</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PB3</td>
<td>LCD-E</td>
<td>(LCD-CE)</td>
<td>LCD-SCL</td>
<td></td>
</tr>
<tr>
<td>PB4</td>
<td>LCD-D4</td>
<td>LCD-REST</td>
<td>LCD-SDA</td>
<td></td>
</tr>
<tr>
<td>PB5</td>
<td>LCD-D5</td>
<td>LCD-RS</td>
<td></td>
<td>ISP-MOSI</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Rotary encoder 2</td>
</tr>
<tr>
<td>PB6</td>
<td>LCD-D6</td>
<td>LCD-SCLK</td>
<td></td>
<td>ISP-MISO</td>
</tr>
<tr>
<td>PB7</td>
<td>LCD-D7</td>
<td>LCD-SI</td>
<td></td>
<td>ISP-SCK</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Rotary encoder 1</td>
</tr>
</tbody>
</table>

Table 2.5. Different variations of the display port assignments

You can also connect a display with the ST7108 controller into the ATmega644 of ATmega1284 by using a little circuit as shown in figure [2.22]. You should also respect the different pin assignments of display modules with ST7108 controllers as shown in table [2.3] at page [18]
Figure 2.22. Connection of a ST7108 Controller to a ATmega644/1284
2.8 Buildup of a tester with ATmega1280 or Arduino Mega

The basic circuit of the tester can also be built with an Arduino Mega with an ATmega1280 or ATmega2560 microcontroller with a shield. The required connections are shown in figure 2.24. The names for the connections of the display signals of the Arduino are shown with green color.

Figure 2.23. Extended Transistor Tester circuit with ATmega644
Components with red color identification are not required for operating. The ATmega2560 controller has many connectors, but only one connector has the required functions for both techniques of the frequency measurement. The connector must be used as clock input for a build in counter and must also be used as interrupt source for change of signal level. This feature is only available for the pin PE6 (T3/INT6). The other clock inputs of counters PD7 (T0), PD6 (T1), PH7 (T4) and PL2 (T5) can not be used as interrupt source for status change. Unfortunately the PE6 pin is not connected to a pin of the Arduino female connector strip. The PE5 pin (7) is connected to the connector 3 of the PWM socket strip and can be jumpered with the PE6 pin (8) of the ATmega2560. The output signal of the frequency generation is available at the PB6 (OC1B) pin. This pin is connected to the connector 12 of the PWM socket strip. The ISP-connector is not required, because the program can be loaded with the bootloader and the USB interface to the ATmega. With the bootloader there is always a little delay for the power up start of the program.

![Transistor Tester Circuit Diagram](image_url)

Figure 2.24. TransistorTester circuit with ATmega1280, ATmega2560 or Arduino Mega

Of course you can connect all supported displays also to the ATmega1280 or ATmega2560 as shown in table 2.6.
<table>
<thead>
<tr>
<th>Port</th>
<th>Character</th>
<th>ST7565 seriell</th>
<th>ST7920 seriell</th>
<th>ST7108 seriell</th>
<th>SSD1306 I²C</th>
<th>additional function</th>
</tr>
</thead>
<tbody>
<tr>
<td>PA0</td>
<td>LCD-D4</td>
<td>LCD-REST</td>
<td>LCD-RESET</td>
<td>HC595-RCK</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PA1</td>
<td>LCD-D5</td>
<td>LCD-RS</td>
<td>LCD-CS2</td>
<td></td>
<td></td>
<td>rotary encoder 2</td>
</tr>
<tr>
<td>PA2</td>
<td>LCD-D6</td>
<td>LCD-SCLK</td>
<td>HC164-CLK</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PA3</td>
<td>LCD-D7</td>
<td>LCD-SI</td>
<td>LCD-CS1</td>
<td></td>
<td></td>
<td>rotary encoder 1</td>
</tr>
<tr>
<td>PA4</td>
<td>LCD-RS</td>
<td>LCD-B0</td>
<td>LCD-RS</td>
<td>HC164-SER</td>
<td>LCD-SDA</td>
<td></td>
</tr>
<tr>
<td>PA5</td>
<td>LCD-E</td>
<td>LCD-CE</td>
<td>LCD-EN</td>
<td>LCD-EN</td>
<td>LCD-SCL</td>
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</tr>
<tr>
<td>PA7</td>
<td>key signal</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 2.6. Connections for different display to the ATmega1280/2560 processors

2.9 Programming of the microcontroller

I release the software for the microcontroller with source code. The development is done with Linux operation system (Ubuntu) and is controlled with a Makefile. The Makefile makes sure, that your software will be compiled with the prior selected Makefile options. Some constellations are precompiled with the source. Please take a look to the ReadMe.txt file in the directory Software/default and to the chapter 4 at page 44. The result of compilation have the extensions .hex and .eep. Usually the names will be TransistorTester.hex and TransistorTester.eep. The .hex file contains the data for the program memory (flash) of the ATmega processor. The .eep file contains the data for the EEPROM memory of the ATmega. Both data files must be loaded to the correct memory.

Additionally the operating state of the ATmega processor must be programmed with the “fuses”. If you can use my Makefile and additionally the program avrdude, you need no exact knowledge of the details about the fuses. You have only to type “make fuses” if you have no crystal or “make fuses-crystal” if you have installed the 8MHz crystal to your printed board. With the ATmega168 series of the microcontroller you can also use “make fuses-crystal-lp” to use a crystal with the low power mode. Never choose the crystal mode of clock generation, if you don’t have installed the 8MHz crystal. If you are not sure with the fuses, leave them as default set by manufactor and first bring the the tester to operation in this mode. Maybe your program runs too slow, if you use program data compiled for 8MHz operation, but you can correct this later! But a wrong set of fuses may inhibit later ISP-programming.

2.9.1 Using the Makefile with Linux

You can install packages with Debian based Linux versions by using a package manager as synaptic or dpkg. The package “subversion” must be installed for downloading the sources or the documentation from the SVN archive. With the command

```
svn checkout svn://www.mikrocontroller.net/transistortester
```

you can download the complete archive. Of course you can also download only subdirectories of the archive. For using the Makefile in one of the subdirectories you must install the packages make, binutils-avr, avrdude, avr-libc and gcc-avr. Once you must prepare the access to the interfaces for the user. If you open a consol window and you have also connected a ISP programmer with USB interface, you can see the recognized USB devices with the command “lsusb”. A sample of the result of lsusb you can see here:

Bus 001 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub
Bus 002 Device 003: ID 046d:c050 Logitech, Inc. RX 250 Optical Mouse

32
Bus 002 Device 058: ID 03eb:2104 Atmel Corp. AVR ISP mkII
Bus 002 Device 059: ID 2341:0042 Arduino SA Mega 2560 R3 (CDC ACM)
Bus 002 Device 001: ID 1d6b:0001 Linux Foundation 1.1 root hub

A Device 58 is detected here as an AVR ISP mkII type (DIAMEX ALL-AVR). The ID 03eb is a vendor ID and the ID 2104 is a product ID. Both ID’s are required for an entry in the file /etc/udev/rules.d/90-atmel.rules. In this example the file 90-atmel.rules has one line:

```
SUBSYSTEM=="usb", ATTRS{idVendor}=="03eb", ATTRS{idProduct}=="2104", MODE="0660", GROUP="plugdev"
```

This entry allows the access to the USB device 58 for members of the group ”plugdev”. The also detected USB device 59 allows a access to the serial device ”/dev/ttyACM0” for members of the group ”dialout”.

Therefore your user identification should be a member of the group plugdev and also a member of the group dialout. With the command ”usermod -a -G dialout,plugdev $USER” the membership of both groups should be established. Now the program avrdude should have permission to access both devices. In a console window you must first change the directory with the command “cd” to a proper subdirectory of the directory trunk. Now you can change options of the Makefile with any text editor. For compiling the source you must only type the simple command “make”. If the ISP programmer is configured properly in the Makefile, a command “make upload” should result to load the program with the ISP interface to the ATmega. The “fuses” of the ATmega must also be set correctly once. You can achieve this with the command “make fuses” or “make fuses-crystal”. The program avrdude probably reports a error for setting the extended fuse efuse. The reading of unused fuse bits is specified as ”1” for the ATmega, but the avrdude program mask the unused bits, so that it expect a ”0” for all unused bits. Normally the efuse should be set to 0xfc, but avrdude read back 0x04 with the mask. You can change the file avrdude.conf to change the behaviour of avrdude or you can set the efuse to 0x04. The value for all efuses can be set with the identifier EFUSE_VAL at the begin of file setup.mk in the trunk directory. Probably the fuses are also set correctly with the error message.

### 2.9.2 Using the WinAVR package with Windows

If you use the Windows operating system, the easiest way to get a correct programmed ATmega is to use the WinAVR package [16],[17]. With my patch [18] you can also set the fuses by using the Makefile. Of course the avrdude program must support your programmer and the configuration in the Makefile must match to your environment.

The figures [2,25] show the File menu of the graphical user interface of WinAVR for open the file Makefile and for saving the changed Makefile (Save).
The next figures 2.26 show the Tools menu of the Programmer’s Notepad for compiling the program (Make All) and for programming the ATmega (Program) with avrdude.

Figure 2.25. Using of the WinAVR user interface Programmer’s Notepad

Figure 2.26. Using of the WinAVR user interface Programmer’s Notepad
2.10 Troubleshooting

In most cases of problems you will miss the text output to the LCD-display. At first you should check, if the LED was illuminated weak, if you release the Test button.

**Power does not switch on.** If the LED is without light and the VCC power has correct 5V voltage during holding the Test button, the microcontroller does not switch the power correctly. The microcontroller should hold the power by switching the PD6 output to 5V, which is usually done as one of the first actions. If you hold the Test key pressed, the power is switched on anyway. So you can check the value of VCC power and additionally the voltage value of the PD6 output, if you hold the key pressed. If VCC voltage has correct value (5V), but PD6 voltage is below 4V, your microcontroller does not start the program. In this case you should check if the microcontroller flash has been loaded with proper data for your installed type and if ATmega is correctly configured with the fuses. If your ATmega put the PD6 output to 5V and the power does not stay if you release the Test key, it is more difficult to find the reason. First you can shorten the LED and try again. If your Tester now starts, your LED may be faulty or mounted with wrong polarity. If this is not the reason, the current amplification factor of your T3 transistor (BC557C) is insufficient. The current to the base of T3 is lower in the microcontroller state as in the “key pressed” state.

**Nothing is readable on the LCD display** Check the voltage at the contrast pin at the LCD display (pin 3). Adjust to correct value specified in the data sheet of your display and optimize by viewing. If you have a high temperature display type, you must provide a negative contrast voltage for operation. In this case you can use the ICL 7660 device for generating a negative voltage from positive 5V.

The tester software can be configured for many different controller with different connection types. You should check, if your software matches to your mounted display type. If there is no output readable on the LCD and the background light is on, you should disconnect the power and check all four data plus the two control signal connections. If all connection are well, the only reason I see is a unecorrect timing of control signals. This can be caused by a slower LCD controller than expected by the software or the ATmega software runs at wrong clock speed. Please check for which clock speed your programming data was compiled and if the fuses of the ATmega are correct set to that speed. You find the clock parameter in the corresponding Makefile. If the tester is build without the switch off electronic, you can test with a LED connected to the test pins, if the program operates normally. If the LED flickers, the program operates well. The missing text on the LCD must be caused by wrong connection or timing. For some graphical displays the contrast is changeable with a menu function. If you have changed the contrast value, that nothing is readable at the screen, you cannot handle the menu function any more. You can try to read the display from a slanting look to the display, not from the front side. In this case you can try to handle the menu function with this view. Otherwise you can write the EEPROM data new with a ISP programmer to reset the contrast value.

**Something but not all is readable on the LCD display** Check if the .eep data are loaded to the EEPROM memory of ATmega. If all data are loaded correctly, you should check the clock speed of your programming data (Makefile) and ATmega processor settings (fuses).

**Measurement is slow and Capacitors are measured about 8 times too small** You run software compiled for 8MHz clock at real clock speed of 1MHz. Please set the fuses of the ATmega correctly.
**Measurement has strangely values** Check if your programmer is still connected to the ISP-plug. The ISP interface should be disconnected for measuring. Very often the reason of wrong measurements is the use of software compiled with the AUTOSCALE_ADC option and with the option NO_REF_CAP, but the capacitor at the AREF pin has still a value of 100nF. Wrong assembly of components or remaining soft solder flux can disturb the measurements too. Please check with the selftest function of your TransistorTester software if possible. For the details see Chapter [5.3](#).

Otherwise inspect your board visually and check the resistor values with a ohmmeter. You can use the pins of the ATmega for this check, for example to check the R1 you can measure between pin 23 and pin 14. Take a look at the circuit diagram [2.1](#) for details. There is no need to remove the microcontroller, only battery or power supply should be removed before.

**The Tester switch off the power after 2 seconds display time** This condition exists, if the external Pull-Up resistor at the PD7 input is missing or the key button is keep pressed. The software switch off the internal Pull-Up resistors to prevent a influence to the measurement results. Therefore a external Pull-Up resistor (27k) is required.

**Der Tester shows only Vext=xx.xV in row 2** This problem exists, if the Pull-Up resistor at the PD7 input is missing or the key button is keep pressed. Additionally the software is configured without the serial output (without option WITH_UART) and without the internal Pull-Up resistors (with option PULLUP_DISABLE). You should install the Pull-Up resistor at pin PD7.
Chapter 3

Instructions for use

3.1 The measurement operation

Using of the Transistor-Tester is simple. Anyway some hints are required. In most cases are wires with alligator clips connected to the test ports with plugs. Also sockets for transistors can be connected. In either case you can connect parts with three pins to the three test ports in any order. If your part has only two pins, you can connect this pins to any two of the tree test ports. Normally the polarity of part is irrelevant, you can also connect pins of electrolytical capacitors in any order. The measurement of capacity is normally done in a way, that the minus pole is at the test port with the lower number. But, because the measurement voltage is only between 0.3\,V and at most 1.3\,V, the polarity doesn't matter. When the part is connected, you should not touch it during the measurement. You should put it down to a nonconducting pad if it is not placed in a socket. You should also not touch to the isolation of wires connected with the test ports. Otherwise the measurement results can be affected. Then you should press the start button. After displaying a start message, the measurement result should appear after two seconds. If capacitors are measured, the time to result can be longer corresponding to the capacity.

How the transistor-tester continues, depends on the configuration of the software.

**Single measurement mode** If the tester is configured for single measurement mode (POWER_OFF option), the tester shut off automatical after displaying the result for 28 seconds for a longer lifetime of battery. During the display time a next measurement can be started by pressing the start button. After the shut off a next measurement can be started too of course. The next measurement can be done with the same or another part. If you have not installed the electronic for automatic shut down, your last measurement result will be displayed until you start the next measurement.

**Endless measurement mode** A special case is the configuration without automatical shut off. For this case the POWER_OFF option is not set in the Makefile. This configuration is normally only used without the transistors for the shut off function. A external off switch is necessary for this case. The tester will repeat measurements until power is switched off.

**Multi measurement mode** In this mode the tester will shut down not after the first measurement but after a configurable series of measurements. For this condition a number (e.g. 5) is assigned to the POWER_OFF option. In the standard case the tester will shut down after five measurements without found part. If any part is identified by test, the tester is shut down after double of five (ten) measurements. A single measurement with unknown part after a series of measurement of known parts will reset the counter of known measurements to zero. Also a single measurement of known part will reset the counter of unknown measurements to zero. This behavior can result in a nearly endless series of measurements without pressing the start button, if parts are disconnected and connected in periodical manner.
In this mode there is a special feature for the display period. If the start button is pressed only short for switching on the tester, the result of measurement is only shown for 5 seconds. But if you press and hold the start button until the first message is shown, the further measurement results are shown for 28 seconds. The next measurement can started earlier by pressing the start button during the displaying of result.

3.2 Optional menu functions for the ATmega328

If the menu function is selected, the tester start a selection menu after a long key press (>500ms) for additional functions. This function is also available for other processors with at least 32K flash memory. The selectable functions are shown in row two of a 2-line display or as marked function in row 3 of a 4-line display. The previous and next function is also shown in row 2 and 4 of the display in this case. After a longer wait time without any interaction the program leave the menu and returns to the normal transistor tester function. With a short key press the next selection can be shown. A longer key press starts the shown or marked function. After showing the last function "switch off", the first function will be shown next.

If your tester has also the rotary pulse encoder installed, you can call the menu with the additional functions also with a fast rotation of the encoder during the result of a previous test is shown. The menu functions can be selected with slow rotation of the encoder in every direction. Starting of the selected menu function can only be done with a key press. Within a selected function parameters can be selected with slow rotation of the encoder. A fast rotation of the encoder will return to the selection menu.

**frequency** The additional function "frequency" (frequency measurement) uses the ATmega Pin PD4, which is also connected to the LCD. First the frequency is always measured by counting. If the measured frequency is below 25kHz, additionally the mean period of the input signal is measured and with this value the frequency is computed with a resolution of up to 0.001Hz. By selecting the POWER_OFF option in the Makefile, the period of frequency measurement is limited to 8 minutes. The frequency measurement will be finished with a key press and the selectable functions are shown again.

**f-Generator** With the additional function "f-Generator" (frequency generator) the selectable frequencies can be switched with key presses. After selecting the last choice of frequencies, the generator is switched back to the first frequency next (cyclical choice). If the POWER_OFF option is selected in the Makefile, the key must be pressed longer, because a short key press (< 0.2s) only reset the time limit of 4 minutes. The elapsed time is shown with a point for every 30 seconds in row 1 of the display. With periodical short key press you can prevent the time out of the frequency generation. With a long key press (> 0.8s) you will stop the frequency generator and return to the function menu.

**10-bit PWM** The additional function "10-bit PWM" (Pulse Width Modulation) generates a fixed frequency with selectable pulse width at the pin TP2. With a short key press (< 0.5s) the pulse width is increased by 1%, with a longer key press the pulse width is increased by 10%. If 99% is overstepped, 100% is subtracted from the result. If the POWER_OFF option is selected in the Makefile, the frequency generation is finished after 8 minutes without any key press. The frequency generation can also be finished with a very long key press (> 1.3s).
C+ESR@TP1:3 The additional function "C+ESR@TP1:3" selects a stand-alone capacity measurement with ESR (Equivalent Series Resistance) measurement at the test pins TP1 and TP3. Capacities from 2\(\mu\)F up to 50\(m\)F can be measured. Because the measurement voltage is only about 300\(m\)V, in most cases the capacitor can be measured "in circuit" without previous disassembling. If the POWER_OFF option is selected in the Makefile, the count of measurements is limited to 250, but can be started immediately again. The series of measurements can be finished with a long key press.

Resistor meter With the \(\text{1-|\,\,\,|\,\,\,3}\) symbol the tester changes to a resistor meter at TP1 and TP3. This operation mode will be marked with a [R] at the right side of the first display line. Because the ESR measurement is not used in this operation mode, the resolution of the measurement result for resistors below 10\(\Omega\) is only 0.1\(\Omega\). If the resistor measurement function is configured with the additional inductance measurement, a \(\text{1-|\,\,\,\,|\,\,\,|\,\,\,|\,\,\,|\,\,\,3}\) symbol is shown at this menu. Then the resistor meter function includes the measurement of inductance for resistors below 2100\(\Omega\). At the right side of the first display line a [RL] is shown. For resistors below 10\(\Omega\) the ESR measurement is used, if no inductance is found out. For this reason the resolution for resistors below 10\(\Omega\) is increased to 0.01\(\Omega\). With this operation mode the measurement is repeated without any key press. With a key press the tester finish this operation mode and returns to the menu. The same resistor meter function is started automatically, if a single resistor is connected between TP1 and TP3 and the start key was pressed in the normal tester function. In this case the tester returns from the special mode operation to the normal tester function with a key press.

Capacitor meter With the \(\text{1|\,|\,|\,|\,3}\) symbol the tester changes to a capacitor meter function at TP1 and TP3. This operation mode will be marked with a [C] at the right side of the first display line. With this operation mode capacitors from 1\(p\)F up to 100\(m\)F can be measured. In this operation mode the measurement is repeated without key press. With a key press the tester finish this operation mode and returns to the menu. In the same way as with resistors, the tester changes automatically to the capacitor meter function, if a capacitor between TP1 and TP3 is measured with the normal tester function. After a automatically start of the capacitor meter function the tester returns with a key press to the normal tester function.

rotary encoder With the function "rotary encoder" a rotary encoder can be checked. The three pins of the rotary encoder must be connected in any order to the three probes of the transistor tester before the start of the function. After starting the function the rotary knob must be turned not too fast. If the test is finished successfully, the connection of the encoder switches is shown symbolic in display row 2. The tester finds out the common contact of the two switches and shows, if the indexed position has both contacts in open state (’o’) or in closed state (’C’). A rotary encoder with open switches at the indexed positions is shown in row 2 for two seconds as ”1-/-2-/-3 o”. This type of encoder has the same count of indexed positions as count of pulses for every turn. Of course the pin number of the right common contact is shown in the middle instead of ‘2’. If also the closed switches state is detected at the indexed positions, the row 2 of the display is also shown as ”1—2—3 C” for two seconds. I don’t know any rotary encoder, which have the switches always closed at any indexed position. The interim state of the switches between the indexed positions is also shown in row 2 for a short time (< 0.5s) without the characters ’o’ or ’C’. If you will use the rotary encoder for handling the tester, you should set the Makefile option WITH_ROTARY_SWITCH=2 for encoders with only the open state (’o’) and set the option WITH_ROTARY_SWITCH=1 for encoders with the open (’o’) and closed (’C’) state at the indexed positions.
Selftest  With the menu function "Selftest" a full selftest with calibration is done. With that call all the test functions T1 to T7 (if not inhibited with the NO_TEST_T1_T7 option) and also the calibration with external capacitor is done every time.

Voltage  The additional function "Voltage" (Voltage measurement) is only possible, if the serial output is deselected or the ATmega has at least 32 pins (PLCC) and one of the additional pins ADC6 or ADC7 is used for the measurement. Because a 10:1 voltage divides is connected to PC3 (or ADC6/7), the maximum external voltage can be 50V. A installed DC-DC converter for zener diode measurement can be switched on by pressing the key. Thus connected zener diodes can be measured also. By selecting the POWER_OFF option in the Makefile and without key pressing, the period of voltage measurement is limited to 4 minutes. The measurement can also be finished with a extra long key press (> 4 seconds).

Contrast  This function is available for display controllers, which can adjust the contrast level with software. The value can be decreased by a very short key press or left turn with the rotary encoder. A longer key press (> 0.4s) or a right turn of the rotary encoder will increase the value. The function will be finished and the selected value will be saved nonvolatile in the EEprom memory by a very long key press (> 1.3s).

Show data  The function „Show Data“ shows besides the version number of the software the data of the calibration. These are the zero resistance (R0) of the pin combination 1:3, 2:3 and 1:2 . In addition the resistance of the port outputs to the 5V side (RiHi) and to the 0V side (RiLo) are shown. The zero capacity values (C0) are also shown with all pin combinations (1:3, 2:3, 1:2 and 3:1, 3:2 2:1). Next the correction values for the comparator (REF_C) and for the reference voltage (REF_R) are also shown. With graphical displays the used icons for parts and the font set is also shown. Every page is shown for 15 seconds, but you can select the next page by a key press or a right turn of the rotary encoder. With a left turn of the rotary encoder you can repeat the output of the last page or return to the previous page.

Switch off  With the additional function "Switch off" the tester can be switched off immediately.

Transistor  Of course you can also select the function "Transistor" (Transistor tester) to return to a normal Transistor tester measurement.

With the selected POWER_OFF option in the Makefile, all additional functions are limited in time without interaction to prevent a discharged battery.

3.3  Selftest and Calibration

If the software is configured with the selftest function, the selftest can be prepared by connecting all three test ports together and pushing of the start button. To begin the self test, the start button must be pressed again within 2 seconds, or else the tester will continue with a normal measurement.

If the self test is started, all of the documented tests in the Selftest chapter 5.5 will be done. If the tester is configured with the menu function (option WITH_MENU), the full selftest with the tests T1 to T7 are only done with the "Selftest" function, which is selectable as menu function. In addition the calibration with the external capacitor is done with every call from function menu, otherwise this part of calibration is only done first time. Thus the calibration with the automatically started selftest (shorted probes) can be done faster. The repetition of the tests T1 to T7 can be avoided, if the start button is hold pressed. So you can skip uninteresting tests fast and you can
watch interesting tests by releasing the start button. The test 4 will finish only automatically if you separate the test ports (release connection).

If the function AUTO_CAL is selected in the Makefile, the zero offset for the capacity measurement will be calibrated with the selftest. It is important for the calibration task, that the connection between the three test ports is released during test number 4. You should not touch to any of the test ports or connected cables when calibration (after test 6) is done. But the equipment should be the same, which is used for further measurements. Otherwise the zero offset for capacity measurement is not detected correctly. The resistance values of port outputs are determined at the beginning of every measurement with this option.

A capacitor with any capacity between 100\(nF\) and 20\(\mu F\) connected to pin 1 and pin 3 is required for the last task of calibration. To indicate that, the message \(1\rightarrow 3 > 100nF\) is shown in row 1 of the display. You should connect the capacitor not before the message\(C0=\) or this text is shown. With this capacitor the offset voltage of the analog comparator will be compensated for better measurement of capacity values. Additionally the gain for ADC measurements using the internal reference voltage will be adjusted too with the same capacitor for better resistor measurement results with the AUTOSCALE\_ADC option. If the menu option is selected for the tester and the selftest is not started as menu function, the calibration with the external capacitor is only done for the first time calibration. The calibration with the external capacitor can be repeated with a selftest call as menu selection.

The zero offset for the ESR measurement will be preset with the option ESR.ZERO in the Makefile. With every self test the ESR zero values for all three pin combinations are determined. The solution for the ESR measurement is also used to get the values of resistors below 10\(\Omega\) with a resolution of 0.01\(\Omega\).

### 3.4 special using hints

Normally the Tester shows the battery voltage with every start. If the voltage fall below a limit, a warning is shown behind the battery voltage. If you use a rechargeable 9\(V\) battery, you should replace the battery as soon as possible or you should recharge. If you use a tester with attached 2.5\(V\) precision reference, the measured supply voltage will be shown in display row two for 1 second with "VCC=x.xxV".

It can not repeat often enough, that capacitors should be discharged before measuring. Otherwise the Tester can be damaged before the start button is pressed. If you try to measure components in assembled condition, the equipment should be allways disconnected from power source. Furthermore you should be shure, that no residual voltage reside in the equipment. Every electronical equipment has capacitors inside!

If you try to measure little resistor values, you should keep the resistance of plug connectors and cables in mind. The quality and condition of plug connectors are important, also the resistance of cables used for measurement. The same is in force for the ESR measurement of capacitors. With poor connection cable a ESR value of 0.02\(\Omega\) can grow to 0.61\(\Omega\). If possible, you should connect the cables with the test clips steady to the tester (soldered). Then you must not recalibrate the tester for measuring of capacitors with low capacity values, if you measure with or without the plugged test cables. For the calibration of the zero resistance there is normaly a difference, if you connect the three pins together directly at a socket or if you connect together the test clips at the end of cables. Only in the last case the resistance of cables and clips is included in the calibration. If you are in doubt, you should calibrate your tester with jumpers directly at the socket and then measure the resistance of shorten clips with the tester.

You should not expect very good accuracy of measurement results, especially the ESR measurement and the results of inductance measurement are not very exact. You can find the results of my
3.5 Components with problems

You should keep in mind by interpreting the measurement results, that the circuit of the TransistorTester is designed for small signal semiconductors. In normal measurement condition the measurement current can only reach about 6mA. Power semiconductors often make trouble by reason of residual current with the identification an the measurement of junction capacity value. The Tester often can not deliver enough ignition current or holding current for power Thyristors or Triacs. So a Thyristor can be detected as NPN transistor or diode. Also it is possible, that a Thyristor or Triac is detected as unknown.

Another problem is the identification of semiconductors with integrated resistors. So the base-emitter diode of a BU508D transistor can not be detected by reason of the parallel connected internal 42Ω resistor. Therefore the transistor function can not be tested also. Problem with detection is also given with power Darlington transistors. We can find often internal base-emitter resistors, which make it difficult to identify the component with the undersized measurement current.

3.6 Measurement of PNP and NPN transistors

For normal measurement the three pins of the transistor will be connectet in any order to the measurement inputs of the TransistorTester. After pushing the start button, the Tester shows in row 1 the type (NPN or PNP), a possible integrated protecting diode of the Collector-Emitter path and the sequence of pins. The diode symbol is shown with correct polarity. Row 2 shows the current amplification factor $B$ or $h_{FE}$ and the current, by which the amplification factor is measured. If the common emitter circuit is used for the $h_{FE}$ determinatation, the collector current $I_c$ is output. If the common collector circuit is used for measuring of the amplification factor, the emitter current $I_e$ is shown. Further parameters are shown for displays with two lines in sequence, one after the other in line 2. For displays with more lines further parameters are shown directly until the last line is alreadly used. When the last line is alreadly used before, the next parameter is shown also in the last line after a time delay automatically or earlier after a key press. If more parameters are present than alreadly shown, a + character is shown at the end of the last line. The next shown parameter is anyway the Base-Emitter threshold voltage. If any collector cutoff current is measurable, the collector current without base current $I_{CE0}$ and the collector current with base connected to the emitter $I_{CE}ES$ is also shown. If a protecting diode is mounted, the flux voltage $U_f$ is also shown as last parameter.

With the common Emitter circuit the tester has only two alternative to select the base current:

1. The 680Ω resistor results to a base current of about 6.1mA. This is too high for low level transistors with high amplification factor, because the base is saturated. Because the collector current is also measured with a 680Ω resistor, the collector current can not reach the with the amplification factor higher value. The software version of Markus F. has measured the Base-Emitter threshold voltage in this ciruit ($U_f=...$).

2. The 470kΩ resistor results to a base current of only 9.2µA. This is very low for a power transistor with low current amplification factor. The software version of Markus F. has identified the current amplification factor with this circuit ($h_{FE}=...$).

The software of the Tester figure out the current amplification factor additionally with the common Collector circuit. The higher value of both measurement methodes is reported. The common
collector circuit has the advantage, that the base current is reduced by negative current feedback corresponding to the amplification factor. In most cases a better measurement current can be reached with this method for power transistors with the 680Ω resistor and for Darlington Transistors with 470kΩ resistor. The reported Base - Emitter threshold voltage $U_f$ is now measured with the same current used for determination of the current amplification factor. However, if you want to know the Base - Emitter threshold voltage with a measurement current of about $6m_A$, you have to disconnect the Collector and to start a new measurement. With this connection, the Base - Emitter threshold voltage at $6m_A$ is reported. The capacity value in reverse direction of the diode is also reported. Of course you can also analyse the base - collector diode.

With Germanium transistors often a Collector cutoff current $I_{CE0}$ with currentless base or a Collector residual current $I_{CES}$ with base hold to the emitter level is measured. Only for ATmega328 processors the Collector cutoff current is shown in this case at the row 2 of the LCD for 5 seconds or until the next keypress before showing the current amplification factor. With cooling the cutoff current can be reduced significant for Germanium transistors.

### 3.7 Measurement of JFET and D-MOS transistors

Because the structure of JFET type is symmetrical, the Source and Drain of this transistors can not be differed. Normally one of the parameter of this transistor is the current of the transistor with the Gate at the same level as Source. This current is often higher than the current, which can be reached with the measurement circuit of the TransistorTester with the 680Ω resistor. For this reason the 680Ω resistor is connected to the Source. Thus the Gate get with the growing of current a negative bias voltage. The Tester reports the Source current of this circuit and additionally the bias voltage of the Gate. So various models can be differed. The D-MOS transistors (depletion type) are measured with the same method.

### 3.8 Measurement of E-MOS transistors

You should know for enhancement MOS transistors (P-E-MOS or N-E-MOS), that the measurement of the gate threshold voltage ($V_{th}$) is more difficult with little gate capacity values. You can get a better voltage value, if you connect a capacitor with a value of some nF parallel to the gate /source. The gate threshold voltage will be find out with a drain current of about $3.5mA$ for a P-E-MOS and about $4mA$ for a N-E-MOS. The RDS or better $R_{DS_{on}}$ is measured with a gate - source voltage of nearly $5V$, which is probably not the lowest value.
Chapter 4

Configuring the TransistorTester

The complete software for the TransistorTester is available in source code. The compilation of modules is controlled with a Makefile. The development was done at the Ubuntu Linux operating system with the GNU toolchain (gcc version 4.5.3). It should be possible to use other Linux operating systems without problems. To load the compiled data to the flash memory or the EEPROM memory, the tool avrdude (version 5.11svn) was taken by the Makefile, if you call “make upload”. The program avrdude [12] is available for Linux and Windows operating system. The gnu C-compiler gcc is also taken by the AVR studio software and by the WinAVR [10,17] software at the Windows operating system. You can load the program data (.hex and .eep) also with other tools to the ATmega, but only my Makefile version takes care to load the correct data to the choosed processor. Avrdude loads only data to the ATmega if the Signature Bytes of the connected ATmega is identical to the choosed one. If you alter the Makefile, all the software will be compiled new, if you call a “make” or “make upload” command. The software compiled for an ATmega8 does not run on an ATmega168. The software compiled for an ATmega328 does not run on the ATmega168! A exeption from this rule is the software compiled for ATmega168, this data can also be used for an ATmega328 without changes. Be careful, if you don’t use my Makefile.

With the correct options set, my software runs on the unchanged hardware of Markus F. You must set the option PARTNO=M8, NOT the option NO_AREF_CAP and NOT the PULLUP_DISABLE option. The clock rate can also be set to 8MHz with fuses, no crystal is required!

The following options in the Makefile are available to configure the software for your Tester.

**PARTNO** describes the target processor:
- m8 = ATmega8
- m168 or m168p = ATmega168
- m328 or m328p = ATmega328
- m644 or m644p = ATmega644
- m1284p = ATmega1284
- m1280 = ATmega1280
- m2560 = ATmega2560
Example: PARTNO = m168

**UI_LANGUAGE** specifies the favored Language
- LANG_BRASIL, LANG_CZECH, LANG_DUTCH, LANG_ENGLISH, LANG_GERMAN,
- LANG_HUNGARIAN, LANG_ITALIAN, LANG_LITHUANIAN, LANG_POLISH,
- LANG_RUSSIAN, LANG_SLOVAK, LANG_SLOVENE, LANG_SPANISH and
- LANG UKRAINIAN is currently available. The russian or ukrainian language requires a LCD with cyrillic character set.
Example: UI_LANGUAGE = LANG_ENGLISH
**LCD_CYRILLIC** is only needed for a LCD-display with cyrillic character set. The \( \mu \) and \( \Omega \) character is not available with the cyrillic character set. If you specify this option, both characters are loaded to the LCD with software. You should set this option, if your display shows wrong characters instead of \( \mu \) or \( \Omega \).

Example: `CFLAGS += -DLCD_CYRILLIC`

**LCD_DOGM** must be set, if a LCD with ST7036 controller (Type DOG-M) is used for displaying. The LCD-contrast is then set with software commands. If you have changed the contrast value to a wrong value, so that you can not read anything at your display, you should first try to read something from a side look to the display. If this fails also, you should reset the EEPROM to the initial values with a ISP programmer.

Example: `CFLAGS += -DLCD_DOGM`

**FOUR_LINE_LCD** can be used with a 4x20 character display for better using the additional space. Additional parameters, which are shown only short in row 2, will be shown in row 3 and 4 with this option.

Example: `CFLAGS += -DFOUR_LINE_LCD`

**WITH_LCD_ST7665** This option must be used, if a 128x64 pixel LCD is connected with serial interface. For this display type further options must be set, which are described in table 4.1. You can also use the similar SSD1306 controller instead of the ST7565 controller for example. This must be done by setting the variable `WITH_LCD_ST7565` to 1306. A PCF8812 or PCF8814 Controller is also supported, if the Option is set correctly. Also a display with a ST7920 or ST7108 controller can be connected. For the ST7108 controller a additional serial-parallel converter 74HC(T)164 or 74HC(T)595 must be used.

Example: `WITH_LCD_ST7565 = 1`

**LCD_INTERFACE_MODE** For the SSD1306 controller also the I\(^2\)C type interface with address 0x3c can be used instead of the 4-wire SPI interface by setting this option to 2. For the ST7920 controller a special serial interface can be selected by setting this option to 5. If only one connection type is provided for a controller, you need not set the constant `LCD_INTERFACE_MODE`. All currently used values for `LCD_INTERFACE_MODE` and `WITH_LCD_ST7565` are shown in table 4.1.
<table>
<thead>
<tr>
<th>Display-Type</th>
<th>Interface</th>
<th>WITH_LCD_ST7565</th>
<th>LCD_INTERFACE_MODE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Character 16x2, Character 20x4</td>
<td>4-Bit parallel</td>
<td>disabled (0)</td>
<td>disabled (1)</td>
</tr>
<tr>
<td></td>
<td>4-Bit SPI</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>I²C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Graphic ST7565</td>
<td>4-Bit SPI</td>
<td>1 or 7565</td>
<td>disabled (4)</td>
</tr>
<tr>
<td>Graphic ST7565</td>
<td>I²C</td>
<td>1 or 7565</td>
<td>2</td>
</tr>
<tr>
<td>Graphic SSD1306</td>
<td>4-Bit SPI</td>
<td>1306</td>
<td>disabled (4)</td>
</tr>
<tr>
<td>Graphic SSD1306</td>
<td>I²C</td>
<td>1306</td>
<td>2</td>
</tr>
<tr>
<td>Graphic ST7920</td>
<td>4-Bit parallel</td>
<td>7920</td>
<td>disabled (1)</td>
</tr>
<tr>
<td>Graphic ST7920</td>
<td>2-Bit serial</td>
<td>7920</td>
<td>5</td>
</tr>
<tr>
<td>Graphic ST7108 or KS0108</td>
<td>8-Bit parallel</td>
<td>7108</td>
<td>disabled (6)</td>
</tr>
<tr>
<td></td>
<td>+ 74HCT164</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Graphic PCF8812</td>
<td>SPI</td>
<td>8812</td>
<td>disabled (4)</td>
</tr>
<tr>
<td>Graphic PCF8814</td>
<td>SPI</td>
<td>8814</td>
<td>disabled (4)</td>
</tr>
<tr>
<td></td>
<td>I²C</td>
<td>8814</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>3-line</td>
<td>8814</td>
<td>3</td>
</tr>
<tr>
<td>Graphic ILI9163 128x128 Color</td>
<td>SPI</td>
<td>9163</td>
<td>disabled (4)</td>
</tr>
<tr>
<td>Graphic ST7735 128x160 Color</td>
<td>SPI</td>
<td>7735</td>
<td>disabled (4)</td>
</tr>
</tbody>
</table>

Table 4.1. Number setting for controller and interface mode

The values in brackets are used software internal and are shown for information only. You should not set the values in brackets here in the Makefile.

Example: CFLAGS += -DLCD_INTERFACE_MODE=2

**LCD_SPI_OPEN_COL** With the option LCD_SPI_OPEN_COL the data signals of the SPI interface are not switched to VCC directly. The signals are switched to GND only, for high signals the pullup resistors of the ATmega are used. For the RESET signal a external pull-up resistor is required, if the option PULLUP_DISABLE is set. For the other signals the internal pullup resistors of the ATmega are temporary used, even if option PULLUP_DISABLE is set. Example: CFLAGS += -DLCD_SPI_OPEN_COL

**LCD_I2C_ADDR** The I²C address of the SSD1306 controller can be selected to 0x3d by presetting the constant LCD_I2C_ADDR to 0x3d.
Example: CFLAGS += -DLCD_I2C_ADDR=0x3d

**LCD_ST7565_RESISTOR_RATIO** With this option the resistor ratio for the voltage regulator of the ST7565 controller is set. Usually values between 4 and 7 are practical. The value can be set between 0 and 7.
Example: LCD_ST7564_RESISTOR_RATIO = 4

**LCD_ST7565_H_FLIP** With this option the display content can be flipped in horizontal direction.
Example: CFLAGS += -DLCD_ST7565_H_FLIP = 1

**LCD_ST7565_H_OFFSET** This option can be used to adapt the display window to the used memory area. The controller uses more horizontal pixel (132) as the display window shows (128). Depending of your display module a value of 0, 2 or 4 can be required for proper
**presentation.**

Example: `CFLAGS += -DLCD_ST7565_H_OFFSET = 4`

**LCD_ST7565_V_FLIP** With this option the display content can be flipped in vertical direction.

Example: `CFLAGS += -DLCD_ST7565_V_FLIP = 1`

**VOLUME_VALUE** You can predefine a contrast value for ST7565 or SSD1306 controllers. The value for the ST7565 controller can be between 0 and 63. For the SSD1306 controller you can select a value between 0 and 255.

Example: `CFLAGS += -DVOLUME_VALUE = 25`

**LCD_ST7565_Y_START** With this option you can set the first row correctly to the top of screen. The first row is shifted to the middle of the screen for some display variants. For this variants you can shift the first row to the top of the screen again, if this option is set to 32 (half of the screen height).

Example: `CFLAGS += -DLCD_ST7565_Y_START = 32`

**FONT_8X16** You must select one font size for the ST7565 controller. Selectable are different fonts with the name "FONT_" with appended size information (width X height). Currently the font sizes 6X8, 8X8, 7X12, 8X12, 8X12thin, 8X14, 8X15, 8X16, and 8X16thin are available. Font size 8X16 or 8x16thin is the most efficient use of graphics space for a 128x64 pixel LCD.

Example: `FONT_8X16`

**BIG_TP** The pin numbers for the graphical presentation can be shown bigger with this option.

Example: `CFLAGS += BIG_TP`

**INVERSE_TP** With this option you can select a inverse presentation (white background) of the pin numbers on the graphical display. Because a boarder in required for this presentation, you can not combine this option with the BIG_TP option.

Example: `CFLAGS += INVERSE_TP`

**STRIP_GRID_BOARD** This option adapts the software to a changed port D connection for strip grid printed boards. You can find the details in the chapter hardware 2.1 at page 9. You can also choose alternative assignments of ATmega pins for graphical displays. For the chinese "T5" board you must set the STRIP_GRID_BOARD option to 5. For alternative pin assignments of graphical displays the assignment of the pushbutton signal is unchanged.

Example: `CFLAGS += -DSTRIP_GRID_BOARD`

**WITH_MENU** activated a menu function for a ATmega328. You can select some additional functions with a selection menu, which you can call with a long key press (> 0.5s).

Example: `CFLAGS += -DWITH_MENU`

**WITH_ROTARY_SWITCH** The menu function can be easier controlled with a the extension of a rotary pulse encoder. See the description 2.5 in the Hardware section for details of the required extension. If your rotary pulse encoder has the same count of indexed positions (detent) as pulses of the switch for every turn, you must set the option WITH_ROTARY_SWITCH to 2. If the rotary pulse encoder has twice the count of indexed position, you must set the option WITH_ROTARY_SWITCH to 1. Setting the WITH_ROTARY_SWITCH to 5 selects the highest resolution for the rotary switch. Every cycle of the two switches results to a count of 4. Usually this setting is only usefull for rotary switch encoders without indexed positions. A setting of the WITH_ROTARY_SWITCH to 4 is required for correct handling of two separate push buttons for Up and Down, which are installed instead of the normal rotary encoder switches. Do not use a setting of 4 for normal rotary encoders!

Example: `CFLAGS += -DWITH_ROTARY_SWITCH=1`

47
CHANGE_ROTARY_DIRECTION You can change the direction of the detected rotary direction by hardware swap of the two switch signals or by setting the this option.
Example: CFLAGS += -DCHANGE_ROTARY_DIRECTION

WITH_SELFTEST If you specify this Option, software will include a selftest function. Selftest will be started, if you connect all three probes together and start measurement. If the menu function is selected, only the calibration part of the self test is executed by automatic start with shorted probes. The selftest parts T1 to T7 are only executed, if the selftest is started with menu selection.
Example: CFLAGS += -DWITH_SELFTEST

NO_COMMON_COLLECTOR_HFE disables the hFE measurement of transistors with the common collector circuit. You can save memory to enable the extended selftests T1 to T7 for a ATmega168 processor. By default both measurement circuits for the hFE measurement are enabled, but there is no place in the program memory of the ATmega168 for the extended selftests.
Example: CFLAGS += -DNO_COMMON_COLLECTOR_HFE

NO_COMMON_EMITTER_HFE disables the hFE measurement of transistors with the common emitter circuit. You can save memory to enable the extended selftests T1 to T7 for a ATmega168 processor. By default both measurement circuits for the hFE measurement are enabled, but there is no place in the program memory of the ATmega168 for the extended selftests.
Example: CFLAGS += -DNO_COMMON_EMITTER_HFE

NO_TEST_T1_T7 This option disable the execution of the selftest parts T1 to T7. This tests are usefull to find errors in the hardware like incorrect measurement resistors or isolation problems. If your hardware is well, you can omitt this selftest parts T1 to T7 by setting this option to get a faster calibration. With enabled menu function the selftest parts T1 to T7 are only started by selection of the menu function ”Selftest”. The ATmega168 processor does not use the selftest parts T1 to T7, if both measurement types for hFE determination are used.
Example: CFLAGS += -DNO_TEST_T1_T7

AUTO_CAL The zero offset for capacity measurement will be written additionally to the EEprom with the selftest routine. Additionally the offset voltage of the analog comparator (with option REF_C_KORR) and the voltage offset of the internal reference voltage (REF_R_KORR) will be measured automatically, if you connect a capacitor with a capacity value between 100nF and 20µF to pin 1 and pin 3 after measurement of capacity zero offset. All found values will be written to EEprom and will be used for further measurements automatically. The port output resistance values will be determined at the beginning of each measurement.
Example: CFLAGS += -DAUTO_CAL

FREQUENCY_50HZ At the end of selftest a 50 Hz Signal will be generated on Port 2 and Port 3 for up to one minute. This option should be set only for special cases to check the delay function.
Example: CFLAGS += -DFREQUENCY_50HZ

CAP_EMPTY_LEVEL This option defines the voltage level for discharged capacitor (mV units). You can set the level to higher value as 3mV, if the tester does not finish discharging of capacitors. In this case the tester ends after longer time with the message “Cell!”.
Example: CFLAGS += -DCAP_EMPTY_LEVEL=3
**WITH_AUTO_REF** specifies that reference voltage is read to get the actual factor for capacity measuring of low capacity values (below 40\(\mu F\)).
Example: CFLAGS += -DWITH_AUTO_REF

**REF_C_KORR** specifies a offset for readed reference voltage in mV units. This can be used to adjust the capacity measurement of little capacitors. A correction value of 10 results to about 1 percent lower measurement results. If the option AUTO_CAL is selected together with the WITH_SELFTEST option, the REF_C_KORR will be a offset to the measured voltage difference of the test capacitor and the internal reference voltage.
Example: CFLAGS += -DREF_C_KORR=14

**REF_L_KORR** specifies a additional offset in mV units to the reference voltage for the measurement of inductance values. The REF_C_KORR offset and respectively the offset value from the calibration is additionally used with the inductance measurement. The REF_L_KORR value will be subtracted for measurements without a 68Ω resistor, for measurements with a 680Ω resistor the value will be added. A correction value of 10 will change the result about 1 percent.
Example: CFLAGS += -DREF_L_KORR=40

**C_H_KORR** specifies a correction value for the measurement of big capacitor values. A value of 10 results to 1 percent lower measurement results.
Example: CFLAGS += -DC_H_KORR=10

**WITH_UART** uses the pin PC3 as output for the serial text (V24). If the option is not set, the pin PC3 can be used for reading a external voltage with a 10:1 resistor divider. With this equipment you can check the breakdown voltage of zener diodes, which have more than 4.5V breakdown voltage. This measurement will repeat with 3 measurements per second until you release the Start button.
Example: CFLAGS += -DWITH_UART

**TQFP_ADC6** The Option TQFP_ADC6 uses the additional input ADC6 of the ATmega with TQFP or QFN package instead of the PC3 pin (ADC3). With this option the external voltage input can be used independent of the usage of PC3 pin for serial output. The ADC6 input is then used for the zener diode measurement and for the dialog selectable external voltage measurement for a ATmega328.
Example: CFLAGS += -DTQFP_ADC6

**TQFP_ADC7** The Option TQFP_ADC7 uses the additional input ADC6 of the ATmega with TQFP or QFN package instead of the PC3 pin (ADC3). With this option the external voltage input can be used independent of the usage of PC3 pin for serial output. If this option is used without the option TQFP_ADC6, both the zener diode measurement and the measurement of external voltage with the dialog is done with the ADC7 analog input. If this option is used together with the TQFP_ADC6 option, is the zener diode measurement done with the ADC6 pin and both pins are used for voltage measurement with the dialog of the ATmega328. Both ADC input pins shouls be assembled with a 10:1 voltage divider.
Example: CFLAGS += -DTQFP_ADC7

**WITH_VEXT** enables the measurement of a external voltage with a 10:1 voltage divider. For the ATmega168 or ATmega328 processor usually the PC3 pin is used as input, if no option TQFP_ADC6 or TQFP_ADC7 is set. In this case this option is only possible, if the WITH_UART option is not set.
Example: CFLAGS += -DWITH_VEXT
RMETER\_WITH\_L select for the resistor measurement function, which is selected with a resistor at TP1 and TP3, additionally the measurement of inductance. The operation mode is indicated with a [RL] at the end of the first display line. With the additional test for inductance the measurement time is increased for resistors below 21\(\Omega\) considerably. Also resistors below 10\(\Omega\) will not be measured with the ESR method without this option, because a part with inductance cannot be excluded. Because the ESR measurement method uses short current pulses, parts with inductance cannot be measured. The resistors below 10\(\Omega\) can only be measured with a resolution of 0.1\(\Omega\) without this option, because only with the ESR method a resolution of 0.01\(\Omega\) can be obtained. If this option is set, the previous limitations are not affected, but the measurement time can be longer.
Example: CFLAGS += -DRMETER\_WITH\_L

AUTOSCALE\_ADC enables the automatic scale switchover of the ADC to either VCC or internal reference. Internal reference gives a 2.56\(V\) scale for ATmega8 and a 1.1\(V\) scale for other processors. For the ATmega8 the automatic scale switchover is not used any more.
Example: CFLAGS += -DAUTOSCALE\_ADC

ESR\_ZERO defines a zero offset for ESR measurements. The zero offsets for all three pin combinations will be determined with the selftest and replaces the preset zero offset. This zero offsets will be subtracted from all ESR measurements.
Example: CFLAGS += -DESR\_ZERO=29

NO\_AREF\_CAP tells your Software, that you have no capacitor (100\(nF\)) installed at pin AREF (pin 21). This enables a shorter wait-time for the AUTOSCALE\_ADC scale switching of the ADC. A 1\(nF\) capacitor was tested in this mode without detected errors. Figure 4.1a and 4.1b show the switching time with a 1\(nF\) capacitor. As you can see the switching from 5\(V\) to 1.1\(V\) is much slower than switching back to 5\(V\). If you have still installed the 100\(nF\), switching time will be about factor 100 longer!
Example: CFLAGS += -DNO\_AREF\_CAP

REF\_R\_KORR specifies a offset for the internal ADC-reference voltage in mV units. With this offset a difference by switching from VCC based ADC reference to internal ADC reference for resistor measurement can be adjusted. If you select the AUTO\_CAL option of the selftest section, this value is only a additionally offset to the found voltage difference in the AUTO\_CAL function.
Example: CFLAGS += -DREF\_R\_KORR=10

OP\_MHZ tells your software at which Clock Frequency in MHz your Tester will operate. The software is tested only for 1\(MHz\), 8\(MHz\) and additionally 16\(MHz\). The 8\(MHz\) operation is recommended for better resolution of capacity and inductance measurement.
Example: OP\_MHZ = 8

RESTART\_DELAY\_TICS must be set to 6, if the ATmega168 or ATmega328 is used with the internal RC-oszillator instead of the crystal oscillator. If this value is not preset, the software respects the 16384 clock tics delay for restart from sleep mode with the crystal operation.
Example: CFLAGS += -DRESTART\_DELAY\_TICS=6

USE\_EEPROM specifies if you wish to locate fix text and tables in EEprom Memory. Otherwise the flash memory is used. Recommended is to use the EEprom (option set).
Example: CFLAGS += -DUSE\_EEPROM

EBC\_STYLE specifies, that the output of transistor pin layout is done with format “EBC=...” or “GDS=...”. This way of output save program memory for the ATmega. Without this option
the layout is shown with the format “123=...”, where every point represent a E (Emitter), B (Base) or C (Collector). For FET transistors every point can be a G (Gate), D (Drain) or S (Source). If the sequence of the test pins is not 1, 2 and 3 in the reading direction, you can invert the sequence with the option EBC_STYLE=321. The pin assignment is then shown with style “321=...”, which will better match the usual reading direction, if the testpin sequence is 3,2,1.

Example: CFLAGS += EBC_STYLE

**NO_NANO** specifies that the decimal prefix nano will not be used to display the measurement results. So capacity values will be shown in \( \mu F \) instead of \( nF \).

Example: CFLAGS += NO_NANO

**NO_LONG_PINLAYOUT** can be set to prevent the long style of pin layout for graphical displays like " Pin 1=E 2=B 3=C". If the option is set, the short style is used instead like " Pin 123=EBC".

Example: CFLAGS += NO_LONG_PINLAYOUT

**PULLUP_DISABLE** specifies, that you don’t need the internal pull-up resistors. You must have installed a external pull-up resistor at pin 13 (PD7) to VCC, if you use this option. This option prevents a possible influence of pull-up resistors at the measuring ports (Port B and Port C).

Example: CFLAGS += -DPULLUP_DISABLE

**ANZ_MESS** this option specifies, how often an ADC value is read and accumulated. You can select any value between 5 and 200 for building mean value of one ADC measurement. Higher values result to better accuracy, but longer measurement time. One ADC measurement with 44 values takes about 5\( ms \).

Example: CFLAGS += -DANZ_MESS=25

**POWER_OFF** This option enables the automatic power off function. If you don’t specify this option, measurements are done in a loop infinitely until power is disconnected with a ON/OFF switch. If you have the tester without the power off transistors, you can deselect the option POWER_OFF.

If you have NOT selected the POWER_OFF option with the transistors installed, you can also shut down the tester, if you have selected the WITH_MENU option.

You can also specify, after how many measurements without a founded part the tester will shut down. The tester will also shut down the power after twice as much measurements are done in sequence without a single failed part search. If you have forgotten to unconnect a test part, total discharging of battery is avoided. Specify the option with a form like CFLAGS += -DPOWER_OFF=5 for a shut off after 5 consecutive measurements without part found. Also 10 measurements with any founded part one after another will shut down. Only if any sequence is interrupted by the other type, measurement continues. The result of measurement stay on the display for 28 seconds for the single measurement, for the multiple measurement version display time is reduced to 5 seconds (set in config.h). If the start key is pressed a longer time on power on time, the display time is also 28 seconds for the multiple measurement. The maximum value is 255 (CFLAGS += -DPOWER_OFF=255).

Example 1: CFLAGS += -DPOWER_OFF=5
Example 2: CFLAGS += -DPOWER_OFF

**BAT_CHECK** enables the Battery Voltage Check. If you don’t select this option, the version number of software is output to the LCD instead. This option is usefull for battery powered tester version to remember for the battery change.

Example: CFLAGS += -DBAT_CHECK

51
**BAT_OUT** enables Battery Voltage Output on LCD (if BAT_CHECK is selected). If your 9V supply has a diode installed, use the BAT_OUT=600 form to specify the threshold voltage (mV) of your diode to adjust the output value. Also the voltage loss of transistor T3 can be respected with this option. threshold level does not affect the voltage checking levels (BAT_POOR).

Example 1: CFLAGS += -DBAT_OUT=300
Example 2: CFLAGS += -DBAT_OUT

**BAT_POOR** sets the poor level of battery voltage to the specified 1mV value. The warning level of battery voltage is 0.8V higher than the specified poor level, if the poor level is more than 5.3V. If the poor level is 5.3V or less, the warning level is 0.4V higher. If the poor level is below 3.25V, the warning level is only 0.2V higher than the selected poor level and if the poor level is below 1.3V, the warning level is only 0.1V higher than the specified poor level. Setting the poor level to low values such as 5.4V is not recommended for rechargeable 9V batteries, because this increase the risk of battery damage by the reason of the deep discharge! If you use a rechargeable 9V Battery, it is recommended to use a Ready To Use type, because of the lower self-discharge.

Example for low drop regulator (5.4V): CFLAGS += -DBAT_POOR=5400
Example for 7805 type regulator (6.4V): CFLAGS += -DBAT_POOR=6400

**DC_PWR** This voltage level in mV units specify the battery voltage above which the tester changes to the ”DC_Pwr_Mode”. Normally the tester operates in a battery mode, where all additional functions are limited in time. With the ”DC_Pwr_Mode” the tester runs the additional functions with unlimited time. Because there is no DC-DC converter operating with 0.9V input voltage, the ”DC_Pwr_Mode” is also entered, if the battery voltage is detected below 0.9V.

Example: CFLAGS += -DDC_PWR=9500

**INHIBIT_SLEEP_MODE** disable the use of the sleep mode of the processor. Normally the software uses for longer work breaks the sleep mode to avoid unneeded current consumption. The usage of this sleep mode indeed spare battery capacity, but produce additional stress for the voltage regulator.

Example: INHIBIT_SLEEP_MODE = 1

**PROGRAMMER** select your programmer type for avrdude interface program. The correct selection of this option is needed, if you use the “make upload” or “make fuses” call of this Makefile. For further information please look to the manual pages of avrdude and online documentation [12].

Example: PROGRAMMER=avrisp2

**BitClock** selects the Bit clock period for the Programmer. See the description of the -B parameter of avrdude.

Example: BitClock=5.0

**PORT** select the port where avrdude can reach your microcontroller (atmega). For further information please look to the manual pages of avrdude.

Example: PORT=usb
Additional parameters can be set in the files transistortester.h and config.h. The file config.h contains global settings, defines the port / pin constellation, the clock frequency of the ADC and the resistor values used for measurement. The file Transistortester.h contains the global variables and tables and also the text used for LCD output. Normally there is no reason to change these values.
Chapter 5
Description of the measurement procedures

The simplified schematic of a Input/Output-Port pin of the ATmega is shown in figure 5.1. The PUD switch isolates all “pull up” resistors of the ATmega. The output of a pin can be switched off with the DD switch. The Input can operate regardless to the state of the switch DD. The PORT switch usually defined the output level, but also switches the pull up resistor. Because the Switches PORT and DD can not be changed at the same time but only one after another, the pull up resistors can disturb the measurement. Therefore I prefere to disable the pull up resistors with the PUD switch. Of course all the switches are electronic type and the resistors 19Ω and 22Ω are approximated values.

![Figure 5.1. simplified diagram of each ATmega port pin](image1)

Every of the three terminal probes of your Transistor Tester is build with three ATmega port pins, which is shown as simplified diagram for the terminal probe TP2 (middle of three pins) in figure 5.2.

![Figure 5.2. simplified circuit of each measurement terminal probe TP](image2)

54
Every test pin (measurement port) can be used as digital or analog input. This measurement capability is independent of using the port as output. Every test pin can be switched to output and in this mode it can be directly connected to GND (0V) or VCC (5V), or it can be connected via a 680Ω resistor or a 470kΩ resistor to either GND or VCC. Table 5.1 shows all possible combination of measurements. Notice, that the positive state can be switched directly to VCC (Port C) or it can be connected with the 680Ω resistor to VCC (Port B). The same possibility has the negative state of terminal probe to the GND side. The test state means, that probe can be open (Input), connected with the 470kΩ resistor to VCC or GND, or that the probe can be connected with the 680Ω resistor to VCC or GND.

<table>
<thead>
<tr>
<th>state pin 1</th>
<th>state pin 2</th>
<th>state pin 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>positive</td>
<td>negative</td>
<td>test</td>
</tr>
<tr>
<td>positive</td>
<td>test</td>
<td>negative</td>
</tr>
<tr>
<td>test</td>
<td>negative</td>
<td>positive</td>
</tr>
<tr>
<td>test</td>
<td>positive</td>
<td>negative</td>
</tr>
<tr>
<td>negative</td>
<td>test</td>
<td>test</td>
</tr>
<tr>
<td>negative</td>
<td>positive</td>
<td>test</td>
</tr>
</tbody>
</table>

Table 5.1. all combinations of measurement

If the capacitor measuring is configured for the tester, the tester will try to discharge the capacitors connected at all test pins. If discharge will fail, that means the remaining voltage is too high, the discharging will be aborted after about 12 seconds with the message ”Cell!”. This can also happen, if no capacitor is connected to any test pin. The cause for this can be, that the cut-off voltage is chosen too low for this ATmega. You can choose a higher voltage with the Makefile option CAP_EMPTY_LEVEL.
5.1 Measurement of Semiconductors

The currentflow of the device with currentless control gate (third pin, also called Tristate pin) is to be examined first. The Tristate pin of the device under test is the base or gate for example. One probe pin is selected as the positive side of the device and connected directly to VCC. The other probe pin selectes as negative side of the device. The negative side is connected with the 680 Ω resistor to GND. With fieldeffect transistors the state of the device depends on the voltage of the gate. The Tristate pin is first connected with the 680 Ω resistor for 5 ms to the GND side and the voltage at the negative side is measured. After that the voltage of the negative side is measured again during the Tristate pin switched as input (High Impedance). Then the assumed gate is connected with the 680 Ω resistor for 5 ms to the VCC side and the voltage on the negative side is measured again. If the measured voltage is lower than the first measurement result, this circuit will be assumed as the right one. Then the voltage is measured again with currentless Tristate pin.

If the voltage of the negative pin with fixed Tristate pin is higher than 115 mV and this level is not 100 mV lower than the voltage measured with currentless Tristatepin, a depletion transistor type is assumed. With bipolar transistors, which have a high collector residual current, the residual current with currentless base is usually significantly higher. With the checking of both voltages we can avoid the wrong detection of some Germanium transistors with a higher collector cutoff current as depletion transistors (JFET).

Then additional tests are done to differ N-channel JFET or N-D-MOSFET and P-channel JFET or P-D-MOSFET. Die MOSFET-Versionen können erkannt werden durch das Fehlen von Steuerstrom in jedem TriStatePins Zustand. The MOSFET versions can be differed by the missing of gate current in any state of the TriStatePin.

To get parameters of the depletion types, they will be measured with a 680 Ω resistor at the source pin, as shown in figure 5.3. This measurement will be done instead of the usually measurement of current with the gate hold at source level, because the $I_{DSS}$ current of the FET transistor can often not be reached with the relative high resistance of the 680 Ω resistor.
If the component has no current between positive probe and negative probe without signal at the TristatePin, the next tests are specified in the next section 5.1.1. If current was detected, the next test is described in the diode section 5.1.4.

### 5.1.1 Measurement of PNP Transistor or P-Channel-MOSFET

First the current amplification factor is measured with common collector (emitter follower) for the assumed PNP transistor. The measuring situation is shown in figure 5.4. If the measured voltage at the Base ($U_B$) is above 9 mV with the 680 Ω resistor, the hFE is build as $hFE = \frac{UE - UB}{UB}$. The voltage $UE$ is the difference of the Emitter-voltage to VCC. The difference between the 22 Ω and 19 Ω resistors are not respected. If the $UB$ voltage is below 10 mV, the measurement is done with the 470 kΩ resistor at the base. In this case the current amplification factor is build as $hFE = \frac{UE - 470000}{UB(680 + 22)}$. 
Figure 5.4. hFE measurement of PNP transistor with common collector circuit

Next the tests with common emitter are done for the assumed PNP transistor. The positive side
of component is now direct connected to VCC, the negative side 680 Ω resistor is connected to GND
as shown in Figure 5.5. If the negative side of component has a voltage of above 3.4 V, when the
base side 680 Ω resistor was connected to GND, it must be a PNP transistor or a P-Channel FET.
This can be easy find out by analysing the base voltage. If the base voltage is greater 0.97 V, it
must be a PNP. For measuring the current amplification factor, the 470 kΩ resistor is taken as Base
resistor instead of the 680 Ω. The current amplification factor is build by $h_{FE} = \frac{(U_C - U_C0) \cdot 470000}{U_B \cdot (680 + 19)}$. The voltage UC0 is the voltage at the colletor resistor without base current. The higher current
amplification factor is assumed to be the right one, this one or the one found with the common
collector circuit.

The values found for the PNP are only valid, if a second set of measurements is done. In order to
prevent detecting the PNP in the inverse mode (collector and emitter are swapped), the measurement
with the higher current amplification is taken as the right one. If base voltage is lower than 0.97 V,
it must be a P-E-MOS. In this case the gate threshold voltage is measured by switching the gate
slowly with the 470 kΩ resistor up and down, waiting for a digital input signal change of the Drain
side and then read the voltage of the gate pin.
5.1.2 Measurement of NPN Transistor or N-Channel-MOSFET

The measuring of NPN-Transistors begin in the same way as PNP-Transistors with measuring the current amplification factor in the common collector circuit. First measurement is done with a 680 Ω base resistor switched to VCC. If the voltage at the base resistor ist too low, the 470 kΩ resistor is taken instead. Measurement then continues with the common emitter circuit as shown in figure 5.6.
If the voltage of collector sinks below 1.6 V, when the 680 Ω base resistor is connected to VCC, ist must be a NPN, N-Channel MOSFET or Thyristor/Triac. With two simple tests a Thyristor or Triac can be identified. If the gate pin resistor is connected for 10 ms to GND and than made currentless, the current at the anode should stay. If then the anode resistor is short connected to GND and reconnected to VCC, the Thyristor should not trigger again (no current). Please keep in mind, that only low power Thyristors can be tested, because the holding current of the tester can reach only 6 mA. If both tests attest a Thyristor, further tests with reverse polarity are done to exclude or confirm a Triac.

If neither Thyristor nor Triac could be confirmed, it can be a NPN or N-Channel E-MOSFET. The Base voltage of a NPN Transistor will be near the Emitter voltage, so this type can be identified definitely. The current amplification factor in the common emitter circuit is build by $hFE = \frac{(VCC-UC-UC0) \cdot 470000}{(VCC-UB) \cdot (680+22)}$. If the voltage of the Base or better Gate shows, that there is no or little current, part will be a N-Channel E-MOS (Enhancement MOSFET). In this case the threshold voltage is measured by switching the Gate slowly with the 470 kΩ resistor to VCC and GND, waiting for a digital input signal change of the Drain side and then read the voltage of the Gate pin. This measurement is done eleven times with ADC results accumulated as shown in Figure 5.7. The result is multiplied by four and divided by 9 to get the voltage in mV resolution.
Figure 5.7. measuring of threshold voltage of N-Channel-MOSFET
5.1.3 Simplified flowchart of the transistors tests

Figure 5.8. Flowchart transistor test Part 1, JFET and D-MOS
Figure 5.9. Flowchart transistor test Part 2, BJT and E-MOS
5.1.4 Measurement of Diodes

If current is detected with the pre-tests, the behavior of the part will be checked to be a diode. The flow voltage with the 680 Ω resistor must be between 0.15 V and 4.64 V. The flux voltage with the 680 Ω must be greater than 1.125 times the flux voltage with the 470 kΩ resistor and sixteen times the flux voltage with the 470 kΩ must be greater than the flux voltage with the 680 Ω resistor. Additionally the afterward renewed measurement with the 470 kΩ resistor should not have a higher voltage than the previous measurement with the 680 Ω resistor. I hope, that this behavior identifies always a diode. The identification of a diode by no current flow in the opposite direction is not possible with an inverse parallel diode. If only a single diode is detected, the residual current in reverse direction is measured with the 470 kΩ resistor at 5 V. The resolution is about 2 nA. If the residual current is greater as 5.3 μA (voltage at the 470 kΩ is more than 2.5 V), the measurement
is done with the 680 Ω instead. Then the resolution is only about 1 µA. Furthermore the capacity in reverse direction is also measured for single diodes.

### 5.1.5 Results of different measurements

The following three tables show results of different test probes with one ATmega8, a ATmega168 and a ATmega328 processor. The measurement of the inverse capacity value for the double diode MBR4045PT is only possible with cooling. This will be caused by high residual current of this 40A diode. Also the capacity value of the inverse base emitter diode of the germanium transistor AC128 can only be measured with cooling.

<table>
<thead>
<tr>
<th>Diode Type</th>
<th>Mega8@8MHz</th>
<th>Mega168@8MHz</th>
<th>Mega328@8MHz</th>
</tr>
</thead>
<tbody>
<tr>
<td>1N4148</td>
<td>Diode, 715mV, 1pF</td>
<td>Diode, 718mV, 0pF, 2nA</td>
<td>Diode, 715mV, 1pF, 4nA</td>
</tr>
<tr>
<td>1N4150</td>
<td>Diode, 665mV, 1pF</td>
<td>Diode, 672mV, 1pF, 4nA</td>
<td>Diode, 665mV, 2pF, 6nA</td>
</tr>
<tr>
<td>BA157</td>
<td>Diode, 619mV, 1pF</td>
<td>Diode, 621V, 17pF, 12nA</td>
<td>Diode, 615mV, 18pF, 12nA</td>
</tr>
<tr>
<td>BY398</td>
<td>Diode, 538mV, 16pF</td>
<td>Diode, 541mV, 14pF, 63nA</td>
<td>Diode, 537mV, 15pF, 63nA</td>
</tr>
<tr>
<td>1N4007</td>
<td>Diode, 650mV, 13pF</td>
<td>Diode, 655mV, 10pF, 6nA</td>
<td>Diode, 650mV, 13pF, 6nA</td>
</tr>
<tr>
<td>LED green</td>
<td>Diode, 1.96V, 5pF</td>
<td>Diode, 1.95V, 4pF</td>
<td>Diode, 1.95V, 4pF</td>
</tr>
<tr>
<td>ZPD2.7</td>
<td>2xDi, 743mV, 2.53V</td>
<td>2xDi, 737mV, 2.52V</td>
<td>2xDi, 733mV, 2.51V</td>
</tr>
<tr>
<td>BU508A B+E</td>
<td>Diode, 609mV, 5.15mF</td>
<td>Diode, 611mV, 5.20mF, 0.39nA</td>
<td>Diode, 606mV, 5.25mF, 0.4uA</td>
</tr>
<tr>
<td>BU508A B+C</td>
<td>Diode, 582mV, 256F</td>
<td>Diode, 586mV, 255pF, 21nA</td>
<td>Diode, 587mV, 259pF, 19nA</td>
</tr>
<tr>
<td>AC128 B+E</td>
<td>Diode, 272mV, 0pF</td>
<td>Diode, 277mV, 0pF, 2.2uA</td>
<td>Diode, 273mV, 0pF, 2.3uA</td>
</tr>
<tr>
<td>AC128 B+E cooled</td>
<td>Diode, 349mV, 140pF, 0.57uA</td>
<td>Diode, 349mV, 140pF, 0.57uA</td>
<td></td>
</tr>
<tr>
<td>MBR20100CT</td>
<td>2xDi, 337mV, 337mV</td>
<td>2xDi, 338mV, 338mV</td>
<td>2xDi, 336mV, 335mV</td>
</tr>
<tr>
<td>MBR20100CT cooled</td>
<td>Diode, 337mV, 345pF</td>
<td>Diode, 339mV, 351pF, 29nA</td>
<td>Diode, 337mV, 350pF, 25nA</td>
</tr>
<tr>
<td>MBR4045PT cooled</td>
<td>Diode, 243mV, 1.80nF</td>
<td>Diode, 233mV, 1.94nF, 1.7uA</td>
<td>Diode, 235mV, 1.95nF, 1.8uA</td>
</tr>
<tr>
<td>SK14</td>
<td>Diode, mV, 0pF</td>
<td>Diode, mV, pF, nA</td>
<td>Diode, 263mV, 0pF, 0.57uA</td>
</tr>
<tr>
<td>SK14 cooled</td>
<td>Diode, mV, nF</td>
<td>Diode, mV, pF, nA</td>
<td>Diode, 334mV, 88uF, 4nA</td>
</tr>
<tr>
<td>SF38G</td>
<td>Diode, 519mV, 107pF</td>
<td>Diode, 521mV, 105pF, 2nA</td>
<td>Diode, 516mV, 106pF, 2nA</td>
</tr>
</tbody>
</table>

Table 5.2. measurement results of diode testing
Table 5.3. Measurement results of bipolar transistor testing

<table>
<thead>
<tr>
<th>Transistor Type</th>
<th>Typ</th>
<th>Mega8 common-collector</th>
<th>Mega328 common-collector</th>
<th>Mega328 common-emitter</th>
</tr>
</thead>
<tbody>
<tr>
<td>BU508A</td>
<td>NPN</td>
<td>B=9, 601mV</td>
<td>B=9, 597mV</td>
<td>B=4, 484mV</td>
</tr>
<tr>
<td>2N3055</td>
<td>NPN</td>
<td>B=20, 557mV</td>
<td>B=21, 550mV</td>
<td>B=6, 442mV</td>
</tr>
<tr>
<td>BC639</td>
<td>NPN</td>
<td>B=148, 636mV</td>
<td>B=172, 629mV</td>
<td>B=158, 605mV</td>
</tr>
<tr>
<td>BC640</td>
<td>NPN</td>
<td>B=226, 650mV</td>
<td>B=176, 609mV</td>
<td>B=177, 608mV</td>
</tr>
<tr>
<td>BC517</td>
<td>NPN</td>
<td>B=23.9k, 1.23V</td>
<td>B=24.8k, 1.22V</td>
<td>B=764, 1.23V</td>
</tr>
<tr>
<td>BC516</td>
<td>PNP</td>
<td>B=75.9k, 1.21V</td>
<td>B=76.2k, 1.20V</td>
<td>B=760, 1.23V</td>
</tr>
<tr>
<td>BC546B</td>
<td>NPN</td>
<td>B=285, 694mV</td>
<td>B=427, 687mV</td>
<td>B=369, 683mV</td>
</tr>
<tr>
<td>BC556B</td>
<td>PNP</td>
<td>B=304, 704mV</td>
<td>B=254, 668mV</td>
<td>B=255, 668mV</td>
</tr>
<tr>
<td>AC128 (Ge.)</td>
<td>PNP</td>
<td>B=63, 191mV</td>
<td>B=59, 191mV</td>
<td>B=43, 117mV</td>
</tr>
<tr>
<td>BUL38D</td>
<td>NPNp</td>
<td>B=37, 627mV</td>
<td>B=41, 617mV</td>
<td>B=40, 624mV</td>
</tr>
<tr>
<td></td>
<td>PNPn</td>
<td>B=11, 654mV</td>
<td>B=81, 543mV</td>
<td>B=10, 656mV</td>
</tr>
<tr>
<td>BRY55/200</td>
<td>Thyrist.</td>
<td>0.84V</td>
<td>0.81V</td>
<td>0.82V</td>
</tr>
<tr>
<td>MAC97A6</td>
<td>Triac</td>
<td>0.92V</td>
<td>0.90V</td>
<td>0.90V</td>
</tr>
</tbody>
</table>

Some results are very different to the earlier results of the software of Markus Frejek. For example a darlington transistor BC517 has been measured by the older software with a hFE of 797 instead of 77200 and a base emitter voltage of 1438 mV. This will be caused by the additional measurement of current amplification with the common collector circuit. Also the new version shows the same low hFE result with the common emitter circuit, as you can see in the last column of table 5.3. The base emitter voltage is measured by the older version as separate diode test with 1438 mV. Now the base emitter voltage is measured with the state of current amplification testing (1.20 V). The BUL38D Transistor has a build in protection diode over the anode and cathode of the NPN transistor, by what a parasitical PNP transistor with swapped Base - Collector connection is build. With software revision 1.10k both transistors are detected and marked with a appended p. The right transistor will be found with comparation of the gate - emitter junction capacitance. It is assumed, that the right transistor has the higher junction capacitance. If you hold down the start key during the output of the measurement result, the parameter of the parasitical transistor are shown. With the label PNPn the existance of another transistor will be marked. The parasitical transistor structure is build only by integration of the protection diode nearby the transistor within the same material, not with a external diode.

The following table 5.4 shows the measurement results for germanium transistors, which are extra problematic to measure because of the temperatur dependent and high residual collector current. The results of the original version of Markus F. and the results of the actual 1.10k version are compared together. The 1.10k version for a ATmega328 measures the current amplification factor with common collector and common emitter circuit with respect to the collector residual current, the higher result will be shown. The collector residual current is not respected by earlier versions.
Table 5.4. Measurement results of bipolar junction germanium transistors

<table>
<thead>
<tr>
<th>Transistor Type</th>
<th>Original Version</th>
<th>Mega8@1MHz</th>
<th>Mega168@8MHz</th>
<th>Mega328@8MHz</th>
</tr>
</thead>
<tbody>
<tr>
<td>AC128</td>
<td>PNP, B=52, 279mV</td>
<td>PNP, B=59, 184mV</td>
<td>PNP, B=59, 191mV</td>
<td></td>
</tr>
<tr>
<td>AC116-65</td>
<td>PNP, B=505, 378mV</td>
<td>PNP, B=72, 146mV</td>
<td>PNP, B=72, 149mV</td>
<td></td>
</tr>
<tr>
<td>AC116-145</td>
<td>PNP, B=485, 294mV</td>
<td>PNP, B=146, 161mV</td>
<td>PNP, B=146, 163mV</td>
<td></td>
</tr>
<tr>
<td>AC176-65</td>
<td>NPN, B=98, 235mV</td>
<td>NPN, B=58, 94mV</td>
<td>NPN, B=56, 96mV</td>
<td></td>
</tr>
<tr>
<td>GC122</td>
<td>PNP, B=84, 368mV</td>
<td>PNP, B=55, 117mV</td>
<td>PNP, B=56, 117mV</td>
<td></td>
</tr>
<tr>
<td>GC301</td>
<td>PNP, B=48, 289mV</td>
<td>PNP, B=39, 184mV</td>
<td>PNP, B=39, 188mV</td>
<td></td>
</tr>
<tr>
<td>AD161</td>
<td>NPN, B=360, 230mV</td>
<td>NPN, B=296, 126mV</td>
<td>NPN, B=298, 128mV</td>
<td></td>
</tr>
<tr>
<td>AD162</td>
<td>PNP, B=2127, 280mV</td>
<td>PNP, B=89, 107mV</td>
<td>PNP, B=89, 107mV</td>
<td></td>
</tr>
</tbody>
</table>

In the table 5.5, the results of some field-effect transistor measurements are shown. One measured parameters of the E-type MOS types is the gate-source voltage, by which the digital input of the ATmega connected to the 680 Ω drain resistor changes the state. The other parameter is the gate capacity value. For very fast change of the gate voltage due to a small gate capacity, the detected voltage is slightly inaccurate. With the BS250 the Voltage changes from 2.6 V to 2.5 V, if you connect a additional 10 nF capacitor to the gate-source. For JFET transistors often the characteristic current Idss is specified, the current in the drain when the gate-source voltage is 0 V. Here, however, the current is given by a 680 Ω load resistance at the source side of the JFET. The load resistor generates a reverse voltage Vgs, which is also shown. Due to the symmetrical design of the JFET transistors, the drain and source can not be distinguished.
<table>
<thead>
<tr>
<th>Transistor</th>
<th>Type</th>
<th>Mega8@8MHz</th>
<th>Mega168@8MHz</th>
<th>Mega328@8MHz</th>
</tr>
</thead>
<tbody>
<tr>
<td>ZVN120A</td>
<td>N-E-MOS</td>
<td>D, 1.6V, 147pF</td>
<td>D, 1.5V, 141pF</td>
<td>D, 1.5V, 140pF</td>
</tr>
<tr>
<td>IRF530N</td>
<td>N-E-MOS</td>
<td>D, 3.6V, 1.55nF</td>
<td>D, 3.6V, 1.54nF</td>
<td>D, 3.6V, 1.54nF</td>
</tr>
<tr>
<td>BS170</td>
<td>N-E-MOS</td>
<td>D, 2.6V, 78pF</td>
<td>D, 2.6V, 68pF</td>
<td>D, 2.6V, 68pF</td>
</tr>
<tr>
<td>IRL3803</td>
<td>N-E-MOS</td>
<td>D, 2.3V, 9.81nF</td>
<td>D, 2.3V, 9.71nF</td>
<td>D, 2.3V, 9.74nF</td>
</tr>
<tr>
<td>IRFU120N</td>
<td>N-E-MOS</td>
<td>D, 4.2V, 909pF</td>
<td>D, 4.2V, 913pF</td>
<td>D, 4.2V, 911pF</td>
</tr>
<tr>
<td>BUZT1A</td>
<td>N-E-MOS</td>
<td>D, 3.2V, 714pF</td>
<td>D, 3.2V, 708pF</td>
<td>D, 3.2V, 705pF</td>
</tr>
<tr>
<td>ZVP2106A</td>
<td>P-E-MOS</td>
<td>D, 3.2V, 122pF</td>
<td>D, 3.2V, 115pF</td>
<td>D, 3.2V, 116pF</td>
</tr>
<tr>
<td>IRF5305</td>
<td>P-E-MOS</td>
<td>D, 3.6V, 2.22nF</td>
<td>D, 3.6V, 2.22nF</td>
<td>D, 3.6V, 2.22nF</td>
</tr>
<tr>
<td>BS250</td>
<td>P-E-MOS</td>
<td>D, 2.6V, 53pF</td>
<td>D, 2.6V, 43pF</td>
<td>D, 2.6V, 44pF</td>
</tr>
<tr>
<td>IRFU9024</td>
<td>P-E-MOS</td>
<td>D, 3.5V, 937pF</td>
<td>D, 3.6V, 945pF</td>
<td>D, 3.5V, 933pF</td>
</tr>
<tr>
<td>J310</td>
<td>N-JFET</td>
<td>3.1mA Vgs=2.2V</td>
<td>3.1mA Vgs=2.2V</td>
<td>3.1mA Vgs=2.2V</td>
</tr>
<tr>
<td>2N5459</td>
<td>N-JFET</td>
<td>2.1mA Vgs=1.5V</td>
<td>2.1mA Vgs=1.5V</td>
<td>2.1mA Vgs=1.5V</td>
</tr>
<tr>
<td>BF256C</td>
<td>N-JFET</td>
<td>3.4mA Vgs=2.4V</td>
<td>3.4mA Vgs=2.4V</td>
<td>3.4mA Vgs=2.4V</td>
</tr>
<tr>
<td>BF245A</td>
<td>N-JFET</td>
<td>1.1mA Vgs=0.75V</td>
<td>1.1mA Vgs=0.75V</td>
<td>1.1mA Vgs=0.75V</td>
</tr>
<tr>
<td>BF245B</td>
<td>N-JFET</td>
<td>2.5mA Vgs=1.7V</td>
<td>2.5mA Vgs=1.7V</td>
<td>2.5mA Vgs=1.7V</td>
</tr>
<tr>
<td>BF245C</td>
<td>N-JFET</td>
<td>3.9mA Vgs=2.7V</td>
<td>3.9mA Vgs=2.7V</td>
<td>3.9mA Vgs=2.7V</td>
</tr>
<tr>
<td>J175</td>
<td>P-JFET</td>
<td>3.2mA Vgs=2.2V</td>
<td>3.2mA Vgs=2.2V</td>
<td>3.2mA Vgs=2.2V</td>
</tr>
<tr>
<td>2N5460</td>
<td>P-JFET</td>
<td>0.78mA Vgs=0.54V</td>
<td>0.77mA Vgs=0.54V</td>
<td>0.78mA Vgs=0.54V</td>
</tr>
<tr>
<td>BSS139</td>
<td>N-D-MOS</td>
<td>1.7mA Vgs=1.2V</td>
<td>D, 1.7mA Vgs=1.2V</td>
<td>D, 1.7mA Vgs=1.2V</td>
</tr>
<tr>
<td>BSS169</td>
<td>N-D-MOS</td>
<td>2.6mA Vgs=1.8V</td>
<td>D, 2.6mA Vgs=1.8V</td>
<td>D, 2.6mA Vgs=1.8V</td>
</tr>
<tr>
<td>GP07N120</td>
<td>N-E-IGBT</td>
<td>C=3.81nF Vt=4.2V</td>
<td>C=3.76nF Vt=4.2V</td>
<td>C=3.74nF Vt=4.2V</td>
</tr>
</tbody>
</table>

Table 5.5. measurement results of MOS transistor testing
5.2 Resistor Measurement

Each resistor is measured with four different types of measurement in one current direction. The same resistor is also tested with the same four measurement types in the other current direction. The measurement in the opposite direction is only used to identify a resistor. If mismatch between both measurements is too big, it’s not a resistor.

5.2.1 Resistor Measurement with 680 Ohm Resistors

The measurement of an unknown resistor $R_x$ is done in two ways with the built-in precision 680Ω resistors. The diagram of this measurements for test pin 1 (TP1) and test pin 3 (TP3) are simplified shown in figure 5.11 and figure 5.12 as an example of the six choices of probe combinations.

![Figure 5.11. Measurement type 1 with 680Ω](image)

![Figure 5.12. Measurement type 2 with 680Ω](image)

On the left side test pin 1 is shown and on the right side you can see test pin 3. In both diagrams you see, that the terminal 3 (right side) is connected to VCC, the left side is connected to GND. The direction of current flow through the resistor $R_x$ is always the same. The values of ports switched to output are shown with red color, the values of ports used as input are shown in blue color, the inactive ports are black. In both shown measurement types the current should have the same value, because the sum of resistor values between VCC and GND is identical (if the built in resistors are identical). Usually the measured voltage is not the same, because the sequence of resistors has changed.
The V symbol within the circle marks the ports used for voltage measurement. In both configurations the value of resistor \( R_x \) can be computed with the known resistor values and the measured voltages, if the relation of resistor \( R_x \) and the 680\( \Omega \) is not too high. The theoretical voltage gradient is shown in figure 5.13 where resistor values are shown in logarithmic scale.

\[ \text{Figure 5.13. Voltages of type 1 and type 2 measurements with 680}\Omega \]

The graph of measurement type 1 is shown in figure 5.14a with zoomed scale for the lower resistor range. You can see, that you need a better ADC resolution than the standard 4.9mV resolution at the 5V ADC reference, to get the right resistor value from measured voltage below 2\( \Omega \). There are only three ADC steps from 0\( \Omega \) to 2\( \Omega \). The range switching with the AUTOSCALE_ADC option can help in this case. The same zoomed range of measurement type 2 shows the figure 5.14b. Unfortunately we can not use the higher ADC resolution for measurement type 2 in this range, because the voltage is too high and our ATmega have no differential ADC input. Measurements with the 680\( \Omega \) resistors are taken for building the result of measurements up to 20k\( \Omega \) (Voltage of measurement type 2 will be below 169mV).

For higher resistor values the measurements with the 470k\( \Omega \) resistors are used. The mean value of both measurements is taken as displayed resistor value, if all tests attests, that it is no other type of part. If the AUTOSCALE_ADC function is selected and one of the voltages of the both measurement types is below 0.98V, a weighted average is build with factor four for this value. The other value is weighted with factor one. This is done to respect the factor four better resolution of this measurement. Factor four is only taken for ATmega168 and ATmega328 processors, for the ATmega8 two is taken as weighting factor if voltage is below 0.98V, because the reference voltage for the ADC is here 2.54V instead of 1.1V. If the ATmega has more than 8 KByte flash memory, the voltage measurement at the resistors will be delayed until no more changes are detected or the time limit is reached. With this method big capacitors are no more detected as resistors by mistake and the DC resistance of big inductors will be measured correctly.
5.2.2 Resistor Measurement with 470 kΩ resistors

The next figures [5.15] and [5.16] shows the same measurement procedure for the measurement with the precision 470kΩ resistors. Because the 470kΩ is very big in relation to the port resistor values 22Ω and 19Ω, the port resistor values are ignored for the computing of the resistor value Rx.

For both measurement types with the 470kΩ resistors only one Voltage is measured, because the current is so low, that no voltage difference at the internal port resistors of the ATmega can be measured (as expected). The theoretical voltage gradient is shown in figure [5.17] where the resistor values are again shown in logarithmic scale. The theoretical gradient in this diagram ends at 100MΩ, but the resulting value of the Tester is limited to 60MΩ, otherwise the Tester assumes that no resistor is connected. The weighted average of both measurement types is taken as result with the same rules described for the measurements with the 680Ω resistors. For all ATmega processors I had found, that the measured results with the 470kΩ resistors are more exactly, if a constant offset of 350Ω will be added. This offset can be adjusted with the RH_OFFSET define in the config.h file.
5.2.3 Results of the resistor measurements

Figure 5.18 shows the relative errors of the resistor measurements with three ATmega8 microcontrollers. Additionally some results with the original software of Markus F. with one ATmega8 are shown as "Mega8orig" in this figure. More measurements results with ATmega8A and ATmega8L are shown in figure 5.19a and 5.19b. Figure 5.20 shows the same measurements with a ATmega168 microcontroller. Mega168 are the results without the AUTOSCALE_ADC option, Mega168as are the same measurements with the AUTOSCALE_ADC option. With the ATmega168 microcontroller it seems to be possible, that measurements of resistors in the range from 20Ω to 20MΩ can be measured with a tolerance of ±1%. For Measurements below 100Ω you should keep in mind, that any measurement probe with wire have a resistance too. It is better to connect the resistor directly to the terminal pins. If this is not possible, subtract the resistance value of the shortened probe. For example, if your Resistor have a printed value of 30Ω, your tester shows a value of 30.6Ω and the two probes shortened have a value of 0.5Ω, then your resistor has been measured with 30.1Ω. Below a resistance value of 10Ω one resolution step results to a error of more than 1%!
Figure 5.18. Relative error for resistor measurements with ATmega8

Figure 5.19. Relative error for resistor measurements
The figure 5.21a shows the measurement errors of three ATmega168 processors before calibration as points, after the calibration as line. The equivalent measurement errors of three ATmega168A processors are shown in figure 5.21b and the measurement errors of three ATmega168P processors are shown in figure 5.22. The measurement errors of three ATmega328 processors are shown in figures 5.23a and 5.23b. After the automatic calibration the relative measurement errors of resistors between 10Ω – 20MΩ usually are in the limit ±1%. Only one measurement of a 22kΩ resistor with the ATmega328P-13 shows a higher error. Before the calibration errors of some processors are found with ±3%. This will be caused by the AUTOSCALE_ADC switching of the ADC reference. The direct compare of a capacitor voltage below 1 V, once measured with the VCC reference and another once measured with the internal reference, can adjust this error. With this measurement condition the voltage is measured with the same multiplexor channel and the internal bandgap reference is connected to the AREF pin of the ATmega. Unfortunately the direct measurement of the bandgap reference with the special multiplexor channel results to this offset, which can be manually adjusted with the REF_R_KORR option or automatically with the AUTO_CAL option of the selftest. With the AUTO_CAL option the REF_R_KORR value is a additional offset to the automatic find out value!
Figure 5.21. Relative error for resistor measurements with three ATmega168

Figure 5.22. Relative error for resistor measurements with three ATmega168A
Figure 5.23. Relative error for resistor measurements

(a) with three ATmega328

(b) with three ATmega328P
5.3 Measurement of Capacitors

The measurement of capacitor values are done as separate task by measurement of load time after all other measurements. The original software of Markus F. did this with a program loop, which reads the corresponding digital input pin until a switch occurred and count the loop cycles. This has the handicap, that the resolution of time measurement is limited by the time consumption of one loop cycle. This usually was done in all six combinations for all three probe pins. The actual software uses two different ways to get the load time in only three combinations for the three probe pins. The positive side is now always the higher probe number. Only if capacity is measured parallel with a diode, the polarity can be in the other order.

5.3.1 Discharging of Capacitors

You should always discharge the capacitor before connecting it to the tester. The tester additionally discharge the capacitor before any measurement. If the voltage is below 1300mV, the capacitor is shortened by the output pins of the connected ADC port (Port C). I believe that this is legal because every output port has a built in resistance of about 20Ω. The data sheet Figure 149 (page 258) shows voltage drop of output pins up to 2V. Of course I can not guaranty, that no damage can occur. I have tested the function with big capacitors of more than 15mF many times and I have never noticed any problem. The current should be below the specified limit of 40mA and is reduced fast by discharging. Off course damage can occur if you do not discharge a (high voltage) capacitor before connecting it to your tester.

5.3.2 Measurement of big Capacitors

One side of the capacitor is connected to GND. The other side of the capacitor is connected with the 680Ω resistor to VCC for a period of 10ms. Afterwards this probe pin is switched to Input (High Impedance). After this 10ms current pulse the voltage of the capacitor is measured without any current. If the voltage has not reached a minimal value of 300mV, the load pulse is repeated up to 499 times. If after 127 pulses a minimum voltage of 75mV is not reached (about 2s), further load is stopped, because never the 300mV can be reached with the remaining load pulses. Figure 5.24 shows the three phases of measuring the capacity value of a capacitor. The value of the capacity is then computed with the count of load pulses and the reached load voltage from a table. The table contains the factors to get the capacity in nF units from load time and the reached voltage with a spacing of 25mV. Interim value of voltage will be interpolated.
As a result of the low load voltage, the measurement is much faster than the initial software version, because this advantage works also on discharging. So bigger capacitors can be measured. Furthermore a diode, which is parallel connected to the capacitor dont disturb the measurement in most cases, because the flux voltage of most diodes is not reached. Beginning with software version 1.12k a trickery is used to measure the residual voltage of a capacitor before the capacity measurement. Depending on the previous history of the capacitor the residual voltage can be positive or negative. Negative voltages can not be measured with the ADC. For that reason the voltage of the negative test pin is raised with the 680Ω resistor to about 132mV as shown in figure 5.25. With the difference of the voltages measured at both sides of the capacitor the residual voltage can be
build with any polarity. The voltage of the positive test pin remains positive in any case, even if the capacitor have a negative residual voltage of some mV.

Figure 5.25. Measurement of the residual voltage of a capacitor before loading

Figure 5.26a shows the charge and discharge for a 229µF capacitor. The flat top of diagram from load end to discharge begin is caused by the measuring and computing time of the ATmega. Figure 5.26b shows the same measurement for a 5mF capacitor, notice how the time for measurement is grown to about 1.5 seconds inclusive the discharge. The last example shows the capacity measuring of a 15mF capacitor in Figure 5.27.

(a) 229µF Capacitor
(b) 5mF Capacitor

Figure 5.26. Charge and discharge of big Capacitors for measuring
After this capacity measurement the self-discharge of the capacitor will be checked by waiting a proportional period the loading has taken and reading the load voltage again. The measured capacity value is corrected due to this voltage drop. A test with a parallel connection of a 68 µF capacitor and a 2.2 kΩ resistor shows the effectiveness of this method. The measured capacity value without the resistor is 66.5 µF, with the parallel 2.2 kΩ resistor results to a capacity value of 66.3 µF. For comparison here are the results measured with a Peaktech 3315 multimeter: Without the resistor a capacity value of 68.2 µF is measured, with the parallel 2.2 kΩ resistor a value of 192 µF is measured with the multimeter.

5.3.3 Measurement of small Capacitors

If the first 10 ms load pulse has overloaded the capacitor, another technique of measurement is used. The ATmega processor has a build in 16-Bit counter, which can operate at the full clock rate (1 MHz or 8 MHz). This counter has also the feature to save his counter value by a external event. This event can be built by the output of the comparator. The comparator can operate with any ADC input pin and the band gap reference. Figure 5.28 shows a simplified diagram of the measurement situation. So I discharge the capacitor, prepare the comparator to the proper pin input, start the counter at 0 and start immediately the charging of the capacitor with one side connected to GND and the other side connected with the 470 kΩ resistor to VCC. Now I check within a program loop, if the counter flags signals a overflow event or a input capture (external) event. I count the overflow events until I detect the input capture event. In this case I stop the counter and check if I must count a additional overflow, because the counter can’t be stopped by the input capture event.

The input capture counter and the overflow counter built together the total time, from which we can get the capacity with a factor. The actual software can use a table with the theoretical dependency of the load time in respect to the comparator voltage. The table is spaced in 50 mV steps and will be interpolated according to the actual reference voltage. This table will only be acticated with the Makefile option WITH_AUTO_REF. From the build capacity value I subtract a predefined experimental find out constant or a value found by the last selftest with AUTO_CAL option to eliminate the zero offset. The zero offset may vary with printed board type, the used test equipment or processor. The selftest with AUTO_CAL option will find out your zero offset automatically.
I noticed that the reference voltage is permanently somewhat to low, so that you can choose an offset with the Makefile option REF\_C\_KORR. After calibration with the AUTO\_CAL option, the REF\_C\_KORR will only be a offset to the measured difference voltage between loaded capacitor and internal reference. The measured reference voltage will then be corrected (added) by your value (mV units). If option WITH\_AUTO\_REF is not used, the reference voltages of ATmega8, ATmega168 and ATmega328 are applied as noted in the data sheets [2] [3]. A sample measurement of this type is shown in figure [5.29]. The measurement time for the 22\(\mu\)F capacitor is above 2.6s because the 470k\(\Omega\) is used for charging. But discharging is in this case much faster than charging.

![Diagram](image1.png)

**Figure 5.28.** measurement little capacity values with comparator

![Diagram](image2.png)

**Figure 5.29.** Charge and discharge of a 22\(\mu\)F Capacitor for measuring

In principle this technique of measurement can also be done with the 680\(\Omega\) resistor, but because the ADC can’t be used if the comparator is working, I have no chance to monitor the load voltage until the comparator is stopped. If a undetected diode is parallel connected with the capacitor, the load current of the capacitor can be absorbed by the diode (threshold voltage) and the band-gap voltage will never be reached. The method taken in actual software for big capacitors in section 5.3.2 avoids this conceptual bug.
5.3.4 Measurement of the Equivalent Series Resistance ESR

The series resistance ESR [8] is a good indicator for the aging of electrolytical capacitors for example. The figure 5.30 shows a equivalent circuit of a capacitor. The resistor $R_p$ represents the leakage resistance of the capacitor, $ESL$ the equivalent series inductivity and the resistance $ESR$ represents the equivalent series resistance.

![Figure 5.30. Equivalent circuit of a capacitor](image)

Usually the data sheets publish ESR values, which are measured with a frequency of 100 kHz and a temperature of 20°C. The figures 5.31 and 5.32 shows the ESR values of the Panasonic series FC and the "low ESR" series FR. Both series are able to operate up to a temperature of 105°C. The figure 5.33 shows the data of both series with a allowable working stress of 25V. If the series have different types with the same capacity and voltage range, the one with the lowest ESR is taken for the diagram. The values of capacity and ESR of electrolytic capacitors change significant with there operating temperature.

![Figure 5.31. ESR data from the Panasonic data sheet of the series FC](image)
There is no simple way to measure the ESR with a frequency of 100 kHz with the ATmega hardware, because neither the ADC can sample a so high input frequency, nor the existing circuit can support with a 100kHz signal. At next there will be introduced two method’s for the measurement of the ESR, which both manage on the existing circuit. Both method’s use a rectangular signal for the measurement, so that the results will never be the same with the values measured with sinusoidal.
signal. With the first method the measured values are close to those values, which are measured with a 1kHz signal. But the second method has the advantage, that the zero value can be determined with shorted test pads and that additionally the measured ESR is more close to the value measured with 10kHz signal. Currently I have no idea for a measurement method, which can produce a ESR value close to the value of a 100kHz measurement.

The following table should show the dependency of the ESR results from measurement frequency. All capacitors without the 47µF capacitor are from the same FC series of manufacturer Panasonic. The reference values are measured with a Peaktech 2170 LCR meter. All results of the TransistorTester are measured with the method 2 of subchapter 5.3.6. Capacitors with big capacity values are difficult to measure with higher frequencies like 100kHz because the inductance ESL make trouble.

<table>
<thead>
<tr>
<th>Capacitor</th>
<th>Data sheet 100kHz</th>
<th>PeakTech 100kHz</th>
<th>Peaktech 10kHz</th>
<th>PeakTech 1kHz</th>
<th>Transistor-tester</th>
</tr>
</thead>
<tbody>
<tr>
<td>1µF / 50V</td>
<td>2.4</td>
<td>1.27</td>
<td>1.75</td>
<td>4.31</td>
<td>2.1</td>
</tr>
<tr>
<td>2.2µF / 50V</td>
<td>1.8</td>
<td>1.07</td>
<td>1.34</td>
<td>2.76</td>
<td>1.6</td>
</tr>
<tr>
<td>4.7µF / 50V</td>
<td>1.3</td>
<td>1.19</td>
<td>1.40</td>
<td>2.37</td>
<td>1.5</td>
</tr>
<tr>
<td>4.7µF / 50V</td>
<td>1.3</td>
<td>1.19</td>
<td>1.40</td>
<td>2.37</td>
<td>1.5</td>
</tr>
<tr>
<td>10µF / 50V</td>
<td>1.3</td>
<td>1.26</td>
<td>1.45</td>
<td>2.05</td>
<td>1.5</td>
</tr>
<tr>
<td>22µF / 10V</td>
<td>2.0</td>
<td>1.52</td>
<td>1.76</td>
<td>2.24</td>
<td>1.9</td>
</tr>
<tr>
<td>47µF / 63V</td>
<td>?</td>
<td>0.46</td>
<td>0.50</td>
<td>0.63</td>
<td>0.52</td>
</tr>
</tbody>
</table>

Table 5.6. ESR values of different electrolytical capacitors

5.3.5 Measurement of the Equivalent Series Resistance ESR, first way

If the measured capacitor has a capacity of more than 0.45µF, the tester will try to measure the series resistance too. For a capacity of more than 3.6µF the normal clock rate of 125kHz for the Analog-Digital converter is used. For lower capacities the higher clock rate of 500kHz is used to accelerate the measurement. The accuracy of the ADC results will be more worth by the higher clock rate, but this could be accepted by the higher ESR values of capacitors with lower capacity. Otherwise the measurement of ESR with this method is not possible for a capacity of less than 1.8µF at the normal clock rate of 125kHz.

Strictly speaking the ESR of a capacitor depends on the operating frequency and temperature. Usually the value measured with sine wave-form signal of 100kHz is denoted in the data sheets. This measurement can not be done with the ATmega without external equipment. With the subsequent written method the measurement frequency with the standard ADC clock rate will be below 640 Hz with nearly rectangular signal. With 500kHz ADC clock rate the measurement frequency will be 2400 Hz. To get the value of the equivalent series resistance, the voltage of both connections will be measured during loading in one direction with the ADC internal reference voltage (1.1V). After the measurement the load current will be switched off and the voltage of the capacitor is measured again without the current. If this voltage is below 3mV, the sequence of measurement is repeated. The figure shows the corresponding circuits.
Voltage measurement with charge current

Voltage measurement without current

Figure 5.34. Circuit of the ESR measurements of a capacitor

The difference of capacitor voltages with and without current is proportional to the internal resistance of the capacitor. The expected voltage of this difference is so low, that one measurement cannot result to a feasible result. Therefore after this the current will be switched to the opposite direction and the same measurement will be repeated. The whole measurement sequence will be done 128 times and the results of the voltage measurements will be added. So we have three sums of voltages, the voltage $U_{lp}$ at the low side of the capacitor with current, the voltage $U_{hp}$ at the high side of the capacitor with current and the voltage $U_c$ of the high side of the capacitor without current. The sum of voltages at the low side of the capacitor represents the potential drop with the mean load current at the port output resistance $R_{port}$. The voltage difference of the high side and the low side of the capacitor represents the voltage of the capacitor with load current $U_{diff} = U_{hp} - U_{lp}$. The difference $U_{esr} = U_{diff} - U_c$ should represent the voltage drop at the internal resistance of the capacitor with mean load current. We will get the resistance value with the relation of this voltage $U_{esr}$ to the voltage $U_{lp}$, scaled with the known resistance value of the port output $R_{port}$. The scale factor is selected to get a resistance resolution of 0.01Ω: $Resr = \frac{U_{esr} - 10 \cdot R_{port}}{U_{lp}}$.

The figure 5.35 shows a part of the voltage curve of a 4.2$\mu$F capacitor during the ESR measurement. To explain the influence of the ESR, a series 6.8Ω resistor is added to the capacitor. The little voltage break after loading the capacitor is interpreted by software to get the ESR. The greater voltage drop of the measurement to GND potential is caused by the port output resistance of about 20Ω. For this measurement a total ESR of 7.5Ω is reported by the tester, without the series 6.8Ω resistor a ESR of 0.56Ω is found. The figure 5.36 shows the same measurement with higher measurement frequency of a 2.2$\mu$F electrolytical capacitor with a ESR of 6.5Ω.
Figure 5.35. Voltage curve of a 4.2µF capacitor during the ESR measurement

Figure 5.36. Voltage curve of a 2.2µF capacitor during the ESR measurement

The accuracy of the ESR measurement is not very high by different reasons:

1. The voltage measurement at both pins of the capacitor can not be done at the same time, the only way is to do it in sequence. In the interim time between both measurements the load current has changed due to the charge of capacitor. The program tries to compensate this fact with a capacity dependent correction of the low side voltage.

2. The ADC takes the measurement voltage after 1.5 clock ticks after the start of conversion. The conversion begins with the rising edge of the ADC-clock, if the start bit is set. If the charge current will be switched off to early, the ADC takes the wrong voltage for the measurement with current. If the charge current will be switched off to late, the capacitor will take more electric charge, than that of the corresponding measurement with load current. This will cause a too high voltage of the measurement without current. But it is difficult to switch off the current at the right time by software.

3. The port output resistance is used as a reference value by this measurement method, but this resistance value is not exactly known too.
4. The resolution of the ADC is not sufficient to get a resolution of resistance of 0.01Ω. To get the best available resolution of ADC, the internal reference (1.1V) is used for all measurements. The resolution deficit will be attenuated by accumulating a big number of single measurements too.

5. The switching of ports can not be exactly synchronized to the ADC clock with polling of conversion done.

Anyway the results seems to be practical, as shown with the following figure 5.37. The ESR values of the same part measured with the Transistortester vary more than the values measured with the LCR meter. The ESR values from the LCR meter are measured with a frequency of 1kHz or are interpolated for little capacities to 2.4kHz. You must respect the quality of all connection parts. The used cable connections can cause a higher measured resistance value. The plug connectors can also result a higher resistance value. The LCR meter has the advantage of the used Kelvin terminals. Only one capacitor with a capacity below 1µF was a 500nF ceramic type, all others were plastic film capacitors. The only electrolytical capacitor of the test series below 9µF was a 2.2µF capacitor.

![Figure 5.37. ESR measurement results of 15 different ATmega](image)

### 5.3.6 Measurement of the Equivalent Series Resistance ESR, second way

From beginning with software version 1.07k the ESR measurement way is changed to a new measurement method. The different measurement steps are shown in figure 5.39. The difference to the previous way is that the period of current flow through the capacitor is essential shorter. The capacitor is preloaded with a half pulse to the negative direction and is than loaded in a cyclic way in both direction. The timing of the load pulse is so selected, that the middle of the load puls at sample 4 and 8 is pointed to the sample and hold time of the ADC (2.5 clock tics after start of ADC). A complete measurement cycle is shown in figure 5.38. The sums of 255 measurement cycle results is used for getting a result with adequate resolution. A continuing charge of the capacitor in any direction is avoided by the same charge and discharge pulse length and the same circuit. By measuring the reference voltage the capacitor remains currentless. By that this measurement are not time critical. It is only assumed, that the capacitor hold the voltage until the next charge or discharge pulse begins.
Figure 5.38. Timing of a measurement cycle for the new ESR-measurement way
Forward reference measurement

Forward voltage measurement with probe current

Reverse reference measurement

Reverse voltage measurement with probe current

Figure 5.39. More simple ESR measurement of a capacitor
Due to the shorter load pulse not only the ESR of capacitors with lower capacity can be measured, but this way of measurement can also be used for the measurement of resistors with little resistance, if they don’t have a detectable inductance. By doing that, a resolution of 0.01Ω for this resistors can be achieved. Also the zero resistance can be detected by the calibration part of the selftest for all three test pin combination. You should keep in mind, that stable plug sockets or clamping connectors are essential for stable results. The measurement periode is about 900µs, which results to a frequency of about 1.1kHz. Because the load pulse is very short, the measurement result is comparable to measurements with 10kHz. A measurement example with a 10µF foil capacitor, once measured alone and once measures with a 2.7Ω series resistor is shown in figure 5.40. You can see the effect of the additional resistance by comparing both diagrams. You can see also, why the ADC measurement (SH) should point to the middle of the load pulse. With big capacity values the load current is nearly stable during the total pulse length, so you will get the middle voltage at the middle time of the load pulse. With lower capacity values you will get a significant difference, which can be compensated by the known capacity value.

![Figure 5.40. Voltage curve of a 10µF capacitor during new ESR measurement](image)

(a) without series resistance  
(b) with 2.7Ω series resistance

By using the 27µs long charge pulses the ESR of capacitors above 180nF can be determined. For measuring of capacitors with lower capacity the current pulse is shortened to 8µs for version 1.11k. The figures 5.41 show the voltage curve of a 2.2µF capacitor without and with a 2.7Ω series resistor.
Figure 5.41. Voltage curve of a 2.2µF capacitor during new ESR measurement with 8µs charge pulses

Because you can not see the sample and hold time of the ADC in the figures 5.41, the voltage curve is shown zoomed in figures 5.42. The sample and hold time is approximately in the middle of the screen picture.

Figure 5.42. Zoomed voltage curve of a 2.2µF capacitor during new ESR measurement with 8µs charge pulses

The measurement results of the new ESR measurement method is shown in figure 5.43. The ESR values are different from the results shown for the previous measurement procedure in figure 5.37 because the ESR is frequency dependence of the ESR. The reference values are determined with a LCR meter at a measurement frequency of 10kHz.
Figure 5.43. ESR results with 15 different ATmega, method 2

A measurement series with different sized electrolytic capacitors are shown in figure 5.44. The results of a PeakTech 3315 LCR meter of measurements with different frequencies and the results of the TransistorTester are shown together. The resistance is illustrated with logarithmic scale in this diagram. In all cases the results of the TransistorTester is near by the results of the 10kHz measurements of the LCR meter. Only the 500µF/3V capacitor is a older exemplar, all others capacitors are as good as new.

Figure 5.44. Results of the ESR measurements of different electrolytic capacitors

Because the new measurement method can be taken for measuring of resistors with low values, the measurement errors of some resistors below 10Ω with three example of each ATmega type will be shown in figure 5.45.
5.3.7 Voltage loss after a load pulse, $V_{\text{loss}}$

With the measurement of capacitors with big capacity values the voltage loss after the loading is analysed. The reached load voltage is lost with electrolytic capacitors after a short period. This voltage loss can be caused by a parallel connected resistor. But I assume, that this voltage loss of electrolytic capacitors is caused by an internal load dispersion directly after the load pulse. By loading the capacitors with the $470k\Omega$ resistor, as it is done for little capacity values, this dispersion is already done after switching off the current. No voltage loss is detectable for this case. But if you load the same capacitor with a short current pulse, you can also detect the voltage loss for capacitors with lower capacity. The same effect with lower loss can also be noticed for ceramic type capacitors. I have noticed, that capacitors with more than some % voltage loss are suspect. Especially noticeable with respect to the voltage loss are older paper type capacitors, which are for other measurement a problem too. Some measurement examples will be shown in the following table.
In this table you will find, that the capacity of all foil type capacitors can be measured by all instruments with good precision. The capacity values and the quality factor Q of the PeakTech LCR meter are minimum and maximum values of the measurements in the frequency range 100 Hz to 100 kHz. At all examples in the table the voltage loss Vloss of the TransistorTester is big, if the capacitors have a low quality factor. Only in this case the differences of the capacity measurement results are also big. The TransistorTester can only determine the voltage loss, if the measured capacity is more than 5000 pF.

### 5.3.8 Separate capacity and ESR measurement

The separate capacity measurement and the afterwards measured ESR is only available for ATmega with sufficient memory with the handling dialog. This way of measurement is usefull for measurement of capacitors in the circuit without desoldering. Please take care, that all capacitors of the printed board are discharged before starting any measurement! To realize the measurement in the soldered state, the measurement voltage is hold to a low level of a little above 300 mV only. In addition to that the measurement is only done with the 680Ω resistor to prevent a big effect of connected components on the printed board. To enable the measurement of capacitors with little capacity value, the first load pulse is only 200 µs short. If the loaded voltage let expect, that the 300 mV would not be reached with a load pulse of 2 ms, the next load pulse is done with 2 ms length. When the capacity value of the measured capacitor is very high, the voltage grow is still low with the 2 ms pulse. In this case the next load pulse(s) will be done with 20 ms length. If the loaded Voltage grow near to 300 mV, the shorter load pulses will be used again. The total time of load pulses is added and after the load voltage has passed over 300 mV, the capacity value is computed from load time and the loaded voltage. With this method capacity values of a little below 2 µF can be measured. The upper limit for the capacity values is given with the restricted load time of 2.5 s to about 50 mF. If the capacity value is successfully measured, the ESR value of the capacitor is measured with the method already described in section 5.3.6. The result is shown only short and then the next measurement is started immediately. The series of measurement is stopped after 250 measurements or after pressing the start key. After finishing the measurements the program returns to the handling dialog.
5.3.9 Results of Capacitor measurement

The results of my capacity measurements are shown in figure 5.46 for three ATmega8 processors. Additionally some values of original software are shown with a correction factor of 0.88 (-12%). Other measurement results of different ATmega8 versions are shown in figure 5.47a and 5.47b. The results of the measurement of the same capacitors for a ATmega168 is shown in figure 5.48. The base for the error computing are the measurement results of a PeakTech 2170 RCL-meter, not the printed value of the parts. A part of the relative high measurement difference is caused by the too high measurement frequency of the RCL-meter for big electrolytical capacitors. On the other side the bad quality factor of the electrolytical capacitors may cause another percentage.

Figure 5.46. Error in % for capacitor measurements with ATmega8

Figure 5.47. Relative error of capacitor measurement
Figure 5.48. Error in % for capacitor measurements with ATmega168

Figure 5.49 illustrates, how difficult it is to choose the right base for the capacity measurement. All measurement results are compared with the best estimated value of the capacitors. The gradient „Multimeter“ shows the differences of the Peaktech 3315 Multimeter results. The next gradient „LCR“ shows the differences of the Peaktech 2170 LCR-Meter results, which is taken from best frequency approach. To compare this results to the results of a ATmega168 equipped Transistor-Tester the gradient „ATmega168as“ is also shown. I beleive, that this errors are not real measurement errors of the particular equipment, because my best estimated value are also not the real capacity value of the capacitors.

Figure 5.49. Comparison of capacity measurement results of Multimeter, LCR-meter and ATmega168

The differences of measurements of three different ATmega168 processors are shown in figure 5.50a
In this case the results of the LCR meter is taken as base of comparison. The same results of three different ATmega168A processors are shown in figure 5.50b and three different ATmega168PA processors are shown in figure 5.51. The results of three ATmega328 are additionally shown in figure 5.52a and the results from three ATmega328P are shown in figure 5.52b. At this only the zero value of the capacity measurement of 39pF is respected, all other facility to correct the results are not used. This zero value includes the \(2 - 3\mu F\), which are caused by the 12cm long cable with the clips. The board layout can cause a different zero value, I have fixed this zero value with the board "DG2BRS V 5.2.1".

![Figure 5.50. capacity measurement error, not calibrated](image)

![Figure 5.51. capacity measurement error of three ATmega168PA, not calibrated](image)
To get the best accuracy you must adapt the software to the individual characteristic of your ATmega exemplar. For this you can set a correction voltage $\text{REF}_C\text{KORR}$ for the comparator, which will be used for measurement of little capacity values. A correction of $1\text{mV}$ will reduce the measurement results to $0.11\%$. For big capacity values you can specify with the per mill value $C_H\text{KORR}$, how much your capacity values are measured too big. Because the capacitors with big values are most electrolytic capacitors with worse quality factor, the measurement of the capacity value is difficult. So it is also extra difficult to get the difference to the real value of a capacitor.

Especially with the ATmega168 processors I have noticed a anomaly of measurement results of little capacity values, which depend on the slew rate of the voltage during loading of the capacitor. Figure 5.53 shows the error of the capacity measurement when only the zero value is respected (168-3-A), with correction factor for little capacitors $\text{REF}_C\text{KORR}=66$ as well as the correction factor for big capacitors $C_H\text{KORR}=5$ (168-3-B), plus additional as gradient 168-3-C with a model of the slew rate dependency of little capacitor measurements ($\text{COMP}_S\text{LEW1}=4000$ und $\text{COMP}_S\text{LEW2}=220$). Also the self-discharge of big capacitors is respected with gradient 168-3-C. The component with the slew rate dependent value is computed with $\frac{\text{COMP}_S\text{LEW1}}{cval+\text{COMP}_S\text{LEW2}} - \frac{\text{COMP}_S\text{LEW1}}{\text{COMP}_S\text{LEW2}}$, where $cval$ is the measured capacity value with pF units.
5.3.10 Automatic calibration of the capacitor measurement

The automatic calibration is built in two parts. The first part finds out the zero offset of the capacitor measurement. For that the mean value of the capacity measured without connected capacitor is built. A mean value for all 6 measurement combinations is built with 8 repetitions. After successful determination the zero offsets are written to the EEprom and will be used for further measurements. More difficult was the clearance of the variance of the different ATmega processors for little capacitors (<40µF), which is shown in Figure 5.50a, 5.50b and 5.51. As a significant reason for this is found the different characteristic (Offset voltage) of the analog comparator.

The date of measurement of nine different processors is shown in figure 5.54. The "diff2ref" points show the difference of the voltage of a loaded capacitor of 660nF to the individual internal reference voltages (band gap). Ideally this difference Voltage should be zero, if the analog comparator has stopped the loading by the signal to the processor. The short handling time of the processor should not result to a measurably rising of the capacitor voltage of this relative big capacitor. The "CapErr" points show the estimated measurement errors of each processor out of figure 5.50a, 5.50b and 5.51 with per mill units. It is noticeable, how the "CapErr" points will follow the "diff2ref" points. Therefore the "diff" points show the difference between the particular "CapErr" and "diff2ref" points. With a mean value of the "diff" points we can get a good estimation for the correction of the capacitor measurements together with the difference voltage of the loaded capacitor and the internal reference.

For the second part of adjustment you must connect a capacitor to pin 1 and pin 3. This capacitor should have a good quality factor and should have a capacity between 100nF and 20µF. It should be a film capacitor, as far as possible not a ceramic capacitor und in no case a electrolytic capacitor. You don’t need to know the exact value of this capacitor.

Figure 5.53. Improvement of the capacitor measurement of one ATmega168
Figure 5.54. Date of nine ATmega168 processors

The figures 5.55a, 5.55b, 5.56, 5.57a and 5.57b shows the measurement results of the different processors with a standard software after the auto calibration. The flash of the processors was loaded with the same software, only the Makefile option ”PARTNO = ” must be adapted to the different processor type (”m168”, ”m168p”, ”m328” or ”m328p”) for the avrdude program. After loading the data the selftest was started for each ATmega and a capacitor with 330\(nF\) was connected during test No. 10 to pin 1 and pin 3.

Figure 5.55. capacity measurement error, calibrated
Figure 5.56. capacity measurement error of three ATmega168PA, calibrated

Figure 5.57. capacity measurement error, calibrated

At last I will make more clear the effect of the AUTO_CAL option in the selftest program. The following figure [5.58] shows the results from the three ATmega processors with the biggest error of measurement, one measurement before the calibration and another measurement after the calibration. The points marked with the ending "unc" shows the the errors without calibration. The lines with the ending "cal" shows the error results of the same processors with the same software after the calibration in the selftest section. The reason for the measurement errors for big capacitors (>40μF) is not yet known. All used capacitors for this series of measurements are film capacitors or ceramic capacitors (56pF, 100pF and 3.3nF), no electrolytical capacitors are used.
Figure 5.58. Error of capacitor measurement of three ATmega, before and after the calibration

The circuit with a ATmega644 or ATmega1284 provides a capacitor for calibration at the printed board. The figure 5.59 shows the results of the capacitor measurements with a ATmega1284, with the on board 100\(nF\) ceramic capacitor as well as with a external 220\(nF\) foil capacitor, compared to the results of a ATmega328 on another printed board.

Figure 5.59. Error of capacitor measurements with a ATmega1284 compared to the ATmega328 results
5.4 Measurement of inductance

The measurement of inductance values will be done as separate part with all found resistors with less than 2100Ω. The method of measurement is based on the growing of current by formula

\[ I_l = I_{max} \cdot (1 - \exp\left(\frac{-t}{\tau}\right)) \]

after switching on the current. The time constant \( \tau = \frac{L}{R} \) is proportional to the inductance \( L \), but reverse proportional to the resistor \( R \). The current can only be measured indirectly with the potential drop of a resistor.

Unfortunately the time constant will be reduced additionally by the relative high resistance 680Ω, for that the measurement of little inductance values is additionally made difficult with the 8MHz clock. To get the time constant, the voltage at the 680Ω resistor will be monitored by the analog comparator. If the voltage drop at the 680Ω resistor is higher than the voltage of the internal reference, this event will be notified to the 16-bit counter, which is started at the same time of switching current on. The counter will save the state of this event. If the counter will overrun, this will be counted by the program. After the event, the counter will be stopped by the program and the total time will be build with the saved counter stage and the overflow counter. The positive side of the coil will be switched from VCC to GND and hold in this stage until monitoring of the voltages of both pins shows, that no current is detected. The figure 5.60 shown a simplified diagram of the measurement situation.

![Diagram of measurement setup](image)

Figure 5.60. Measurement of inductances with the comparator

With the supply voltage VCC and the sum of all resistors in the electric circuit the maximum current \( I_{max} \) and from that the percentage of the reference voltage to the maximum voltage at the 680Ω resistor can be calculated \( U_{max} = I_{max} \cdot (680 + 19) \). With the formula

\[ L = \frac{-t \cdot R_{ges} \log(1 - \frac{U_{ref}}{U_{max}})}{\log(1 - \frac{U_{ref}}{U_{max}})} \]

the inductance can be calculated. The natural logarithm will be taken out of a build in table. A inductance resolution of 0.1mH is taken for this type of measurement.

In order to also measure lower inductance values, the 680Ω resistor will be omitted in the current loop, if the resistance value of the inductor is measured with less than 24Ω. Only the output resistance of the port (19Ω) will be used for measurement of the current. In this special case the peak current will be greater than the value, that the specification of the ATmega allows. Because this will be true only for a very short time, I expect no damage of the ATmega ports. For this type of measurement a resolution of inductance of 0.01mH is selected. To avoid a longer time with excessive current, the additional measurement with delayed start of the counter will always be done with the 680Ω resistor. To get better fitting measurement results, a zero offset of 6 is subtract from the counter reading, if
the measurement is done without the 680Ω resistor. Otherwise a zero offset of 7 or 8 is subtracted.

With great inductance values the parasitic capacity can cause a quick rise of current, so that the comparator will respond immediately. To get the value of the inductance anyway, the measurement will be repeated with a delayed start of the counter. With this method the voltage growth caused by the current increase of the inductor will be detected by the analog comparator instead of the current peak of the parasitic capacity. The measurements are always done in both current directions. The program will select the higher result of measurement in the same current direction, but the lower result of the different current direction as the displayed result.

5.4.1 Results of the inductance measurements

The figure [5.61] shows the results of the measurement of different inductors. The Inductors above 1H are relays or primary sides of power transformers, for which measurements are difficult because the iron core has residual remanence.

![Figure 5.61. Error of inductance measurement of 15 different ATmega 104](image)

Figure 5.61. Error of inductance measurement of 15 different ATmega 104.
5.5 Selftest Function

Beginning with release 0.9k I have implemented a self test function. Usage is very simple. If you have installed test terminal with clamps, put all clamps together to a piece of uninsulated wire and press the start button. The program notice the shorten probes and start the self test function, if you confirm within two seconds with pressing the start key. This confirmation is implemented to prevent the tester going automatically to the self test by connecting a defect transistor. After finishing the self test the transistor tester will continue with normal measurement. If no equipment is connected, the program will end with “part unknown or damaged”. You can configure self test only for a ATmega168 or ATmega328. Before the test steps begin, the zero resistance of the connected probes is determined for all three combinations (T1:T3, T2:T3 and T1:T2). This zero resistances will be subtracted for the future ESR and resistance measurements below 10Ω. If the later measured resistance results fall below the particular zero resistance for more than 0.2Ω, the tester will be resetted to “uncalibrated”. This will be marked by a acticated cursor during the tests. The separate steps of the self test function 1 to 7 is displayed on row 1 of the LCD display with the letter T followed by the step number. Every step is repeated 4 times, before the program continues with the next step. But if you hold the start key pressed, when the test cycle is finished, this test is not repeated any more. If you leave the key pressed the total time, every test is executed only once.

Without the AUTO_CAL option only measurement results are displayed in every step, no error analysis are done, you must interpret the results yourself. At this place I will give you an additional important hint. Never do a measurement with connected ISP plug! The ISP interface influences the measurement. Here is the list of currently implemented tests:

1. Measurement of the 1.3V (or 1.1V) reference Voltage (band gap Reference). In row 1 the text “Ref=” and the measured Voltage in mV is displayed. For the ATmega8 the voltage should be near to 1.3V. For the other processors the voltage should be near to 1.1V. The second row shows the resulting factor for the capacity measurement with the 470kΩ resistor.

2. Comparing of the 680Ω resistors. In row 1 the cryptic text “+RL- 12 13 23” is shown. Meaning of this is as follows: The RL is the short form of Resistor Low meaning the 680Ω resistors. The 12 stand for: resistor at pin 1 is connected to VCC (+) and resistor at pin 2 is connected to GND (-). The result of this measurement is displayed in row 2 at the first place as difference to the theoretical value. In row 1 follows now a “13” which means, that the first connection of measurement 1 is still connected with 680Ω to VCC but that the resistor of pin 3 is connected to GND. The result is displayed in the middle place of row 2 as difference to the theoretical value. The last measurement of this test “23,” means that now the resistor at pin 2 is connected to VCC (+) and the resistor of pin 3 is connected to GND. The result of measurement is displayed at the last place of LCR row 2 as difference to the theoretical value. Please remember, that the resolution of the ADC is about 4.88mV! The measurement situation is also shown in figure 5.62. The theoretical value with respect to the internal resistance of the pins should be: \[
\frac{5.62 \cdot 5001 \cdot (19+680)}{(19+680+680+22)} = 2493
\]
3. **Comparing of the 470\,\Omega resistors.** Now the display shows in row 1 “+RH- 12 13 23”. The same procedure as done in step 2 is repeated with the 470\,\Omega resistors (symbols RH). All results are shown as difference to the theoretical value. The theoretical value is this time \( \frac{5001(19+470000)}{(19+470000+470000+22)} = 2500 \) for all combinations.

4. In this step nothing is measured, but the **order is displayed isolate Probe!**, which means that it is time to separate the probes (release from wire). This step will finish only if you release the connections between the probes.

5. **This step tests the capability of GND (-) connected 470\,\Omega resistors (H) to pull the test pins to GND.** Row 1 shows the text “RH-”. Row 2 should display zero for all three pins.

6. **This step tests the capability of VCC (+) connected 470\,\Omega resistors (H) to pull the test pins to VCC (+).** Row 1 shows the text “RH+”. The results are shown as difference to VCC and should be near zero. Great differences from the best value for test 5 and 6 are errors such as isolation problem, flux material or damaged port.

7. **This Step tests the voltages of the 470\,\Omega/680\,\Omega resistor divider.** The voltage difference to the expected voltage of the 470\,\Omega / 680\,\Omega resistor dividers is shown in row 2 of the LCD for all three terminals. Differences of more than some mV can be caused by the assembly of wrong resistor values.

8. **Measuring of internal resistance of pin output switched to the GND signal.** This test and the following tests will only be done, if the option AUTO\_CAL is selected. The internal resistance of the port C outputs switched to GND (-) are measured with the current of to VCC (+) switched 680\,\Omega resistors, see Figure 5.63. Only the three pins of the ADC port are measured, the resistor port B (PB0,PB2 and PB4) can not be measured without hardware modification. Is is assumed that the port resistance of the different ports are nearly identical. The resistor value will be shown in the next test.

---

Figure 5.62. Comparison of 680\,\Omega resistors
9. **Measuring of internal resistance of port outputs switched to the VCC (+)signal.** The needed current is generated with to GND connected 680Ω resistors. It are the same measurements as those in test 8 to the other side as you can see in Figure 5.64. With the following steps the resistance is computed: To get the current, the following is computed: $(VCC - (result of test 8) - (result of test 9))/680$. To get both resistor values, the voltage (result of test 8 or 9) is divided by this current. The result for this test will then be notified in row 1 with the text "RI Hi=", the resistance value (Ω) to the GND side is displayed in row 2 with the text "RI Lo=". Beginning with version 1.06k of the software, the port output resistance values are determined at the beginning of every measurement. The values are only shown by this step.

10. **Measurement of the zero offset of the capacitor measurement.** The zero offset for the capacity measurement with pin combinations 1:3, 2:3 and 1:2 is shown in that order in display row 1 following the “C0 “. Alls three values are shown in pF units. For this measurements no predefined zero offset is respected. The zero offsets of pin combinations in opposite order is also measured. The results will be written to the EEprom, if all values are less than 190pF. This will be notified by the output of “OK” in row 2. The found zero offsets are used for further capacity measurements with respect to the pin combination. If there is any measurement found with a capacity value $20pF$ below the particular zero offset, the tester will be resetted to ”uncalibrated”. This will be noticed by a activated LCD cursor during further tests. Please notice, that changes of the test equipment can cause a new adjustment of the zero offset. If you use wire with clips, the zero offset may be $3pF$ greater compared to a empty socket.
11. **Wait for the connection of a capacitor to pin 1 and pin 3.** The message “1H3 >100nF” is shown in row 1 of LCD. To prepare the measurement of the comparator offset voltage, you must connect a sufficient big capacitor to pin 1 and pin 3. It should be a capacitor with a high quality factor and a capacity between 100\(nF\) and 20\(\mu F\). You should never use electrolytical capacitors, use film capacitors instead.

12. **Measurement of the comparator offset for capacitor measurement adjustment.** To get the offset of the analog comparator, a capacitor must already be connected to pin 1 and pin 3. The capacitor is needed for buffering the load voltage of a capacitor, in order to get the voltage difference of load voltage to the internal reference voltage (band gap). If measurement is successfull, the correction value is short shown with the text “REF_C=” in row 1 of the LCD and written to the EEPROM. You can give a additional offset to the automatic measured value with the REF_C_KORR option.

If you have selected the AUTOSCALE_ADC option, the gain of the ADC readings with the internal reference will be adjusted by comparing a capacitor voltage below 1 V once readed with VCC reference and once readed with the internal reference. The measurement result is shown in row 2 with the text “REF_R=”. Your REF_R_KORR value is a additional offset to this automatic find out difference value.

At the end of test function the text “Test End” is shown in row 1 and the version number of software is shown in row 2. If the Makefile option FREQUENCY_50HZ is set, a 50Hz rectangle signal is generated on pin 2 and the same signal in opposite direction on pin 3. Pin 1 is switched to GND. The current is limited with 680\(\Omega\) resistors. This will be notified by the Output of “50Hz” at the end of row 1 of the LCD display. The 50Hz signal will be generated 30 times for 2 seconds each. You can check the time of the wait calls, if you have an oscilloscope or frequency counter. Figure 5.65 shows the oscillograph curves of both 50Hz output pins with crystal operation.

![Figure 5.65. Oscillograph curve with the 50Hz outputs of Port 2 and 3](image)

If you don’t use the crystal clock version, the result may be inexactly. A exactly clock frequency and wait time are important for measurement of capacity values. You can abort the generation of the 50Hz signal by long time pressing of the start button. Then the program continues with the normal measurement task.
5.5.1 Some Results of the Selftest Function

The results of the selftests of nine different ATmega168 processors and of six ATmega328 processors will be shown in the following figures.

<table>
<thead>
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<th>Test No.</th>
<th>measurement typ</th>
<th>theoretical</th>
<th>figure</th>
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<tr>
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</tr>
<tr>
<td>Test 3</td>
<td>RH-Mean</td>
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<td>5.67b</td>
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<td>5.68a</td>
</tr>
<tr>
<td>Test 6</td>
<td>RH-High</td>
<td>0</td>
<td>5.68b</td>
</tr>
<tr>
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<tr>
<td>Test 9</td>
<td>R out Hi</td>
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<td>5.69b</td>
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<tr>
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<td>Reference correction</td>
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<td>5.71</td>
</tr>
</tbody>
</table>

Table 5.7. Table of the selftest figures

![Reference-Voltages](image)

Figure 5.66. Selftest: Reference-Voltages
Figure 5.67. Selftest: difference to ideal mean voltage

Figure 5.68. Selftest: Input voltage

Figure 5.69. Selftest: Output resistance
Figure 5.70. Selftest: zero offset of the capacity measurement

Figure 5.71. Selftest: correction values after automatic calibration

At last I would like to show you the difference voltages of the external at the AREF pin with a multimeter measured voltages and the internal with the ADC measured voltages of the reference voltages of 15 different ATmega precessors and the found correction voltages (REF_R_Korr) after the automatic calibration in figure 5.72. You can see, that the automatic calibration values nearly follow the external measured values.

Figure 5.72. Selftest: Voltage difference of the internal reference

111
5.6 Measurement of frequency

Beginning with Version 1.10k the frequency measurement can be selected with a control menu. The normal frequency measurement is done with counting the falling edges of input signal T0 (PD4) with counter 0 for one second. For maintaining of a accurate second, the counter 1 is used with a 256:1 prescaler of the CPU frequency. The 16 bit counter of the ATmega can be used up to 16MHz CPU frequency with the prescaler to serve the second period in one pass. For the start and stop of the counter 0 ist the compare register B and A of the counter 1 used. To prevent a unstable delay by polling the compare event signals, for starting and stopping the Interrupt Service of both counter 1 compare events is used. The time delay of both Interrupt Service Routines is nearly equal. To maintain a accurate second period is a constant delay insignificant. With analysing the assembler code, the difference in time can be adjusted.

For frequencies below 25kHz the normal measurement is followed by a measurement of period time. This additional measurement is only followed after a normal frequency measurement. This will be done by measuring the time of a selectable count of the Pin Change interrupts of the PCINT20 (PD4) input with the counter 0. By measuring the period both, the negative puls width and the positive puls width, should be at least 10µs. The counter 0 is used with full clock rate. This results to a resolution of 125ns for 8MHz. With a greater count of measurements periods the resolution can be reduced. By using a measurement period of 125 periods, the middle resolution for one period is 1µs. To prevent the inexactness of start and stop the counter 0, the start of counter 0 is started within the first pin change interrupt of PCINT20 and will be stopped with the last pin change interrupt with the same interrupt service routine. The count of periodes is choosed, that the measurement time is about 10 million clock tics. The part of error from one clock is only 0.1ppm with this choise. With a 8MHz clock the measurement time is about 1.25 seconds. From this mean value of one period a frequency with better resolution is computed too.

For checking the procedure, two testers are measured against each other. First the test frequencies are generated with tester 2 and measured with tester 1. After that the testers are swapped and the measurement is repeated. Figure 5.73 shows the results of both measurement series. The nearly constant errors can be explained with a little frequency difference of both crystals.

![Figure 5.73. Relative errors of frequency measurement](image-url)
Tuning of the crystal frequency is possible with an adjustable capacitor (5-25pF) at the crystal. The one pulse per second (1PPS) from the GPS receiver **UP501** from **Fastrax Ltd.** and from the GPS/GLONASS receiver **GNS701** from **Global Navigation Systems GmbH** has been tested successfully for the calibration of the crystal frequency. The measured period could be adjusted to exactly 1000.000 ms. Only the last digit can toggle with one unit. Of course the frequency of the crystal is temperature dependent. Therefore you can not expect a very good long time stability.

The **Figure 5.74** shows the used circuits with a UM232 USB-serial converter as connection of the receiver modules to a computer. The UM232 converter support the circuit sowohl with both, the 5V and the 3.3V supply voltage from the USB supply voltage. No connection to a computer is required for operating the receivers. Only the 5V supply voltage must be provided to the USB connector.

**Figure 5.74.** Generation of a 1PPS signal with GPS receiver
Chapter 6

Signal generation

The different signal generation modes are only available with a ATmega328 processor. You must also enable the dialog function with the Makefile option WITH_MENU. The menu is called by a long key press. The available functions are shown in the second row of the LCD. You can select the shown function by a long key press. The next function is automatically shown after 5 seconds or after a short key press.

6.1 Frequency Generation

The frequency generation is started, if you select the ”f-Generator” function by a long key press. The frequency output is done with the 680Ω resistor at measurement port TP2. The measurement port TP1 is switched to GND. The frequencies are build with the 16 bit counter from the CPU clock frequency (8MHz or 16MHz). Currently a list of predefined frequencies (2MHz down to 1Hz) can be selected with short key press. If you hold the key pressed for a long time, you can return to the dialog function and select the same or another function.

6.2 Puls width generation

The Puls Width generator is started, if you select the ”10-Bit PWM” function by a long key press. The frequency output is done with the 680Ω resistor at measurement port TP2. The measurement port TP1 is switched to GND. The frequency of the output signal is always the CPU clock divided by 1024. This gives a result of 7812.5Hz for the 8 MHz CPU clock. Only the positive pulse width can be changed by a key press. With a short key press you can increase the positive puls width up to 99% in 1% increments. With a longer key press you can increase the pulse width in 10% increments. The pulse width reaches a value above 99% 100 is subtract from the result. The pulse width 0% generates a very small positive puls width.
Chapter 7

Known errors and unsolved problems

Software Version 1.12k

1. Germanium Diodes (AC128) are not detected in all cases. This is probably caused by the residual current. Cooling of the diode can help to reduce the residual current.

2. With bipolar transistors a collector - emitter protection diode was not detected, if the collector residual current ICE0 is high. The problem was only detected with germanium transistors, which are complemented with an external diode.

3. The current amplification factor of germanium transistors can be measured too high because of the high residual current. In this case the basis emitter voltage will be very low. Cooling of the transistor can help to get a more correct current amplification factor.

4. Capacity value in reverse direction for Power Schottky Diodes such as MBR3045PT can not be measured, if only one diode is connected. The reason is a too big residual current of this diode. Sometimes the measurement is possible by cooling down the device (with cooling spray for example).

5. Here and there a wrong detection of the 2.5V precision reference is reported, when the PC4 pin (27) is unconnected. You can avoid this behaviour with a additional pull up resistor connected to VCC.

6. The diode function of a triac gate can not be examined.

7. Sometimes a problem with the Brown Out level of 4.3V is reported for ATmega168 or ATmega328 processors. This will cause a reset during capacity measurement. A reason is not known. The Resets will disappear, if the Brown Out level is set to 2.7V.

8. With the using of the sleep state of the processor, current of VCC power is changing more than using previous software versions. You should check the blocking capacitors, if you notice any problems. Ceramic capacitors with 100µF should be placed near the power pins of the ATmega. The using of sleep state can be deselected by the Makefile option INHIBIT_SLEEP_MODE.

9. The measurement of tantalum based electrolytical capacitors often make trouble. They can be detected as diode or can also be not detected as known part. Sometimes the measurement with swapped connection can help.

10. The Source and Drain pins can not be detected correctly with JFET’s. The reason is the symmetrical structure of this semiconductors. You can notice this problem with the effect, that the display shows the same layout with the same parameters, if the Source and Drain pins are swapped. I see no way to detect the Source and Drain pin correctly. But interchanging of Source and Drain in any circuit should usually not cause any problem.
Chapter 8
Special Software Parts

Several modifications are done to save flash memory. The LCD-Output of probe-pin numbers was done in the form “lcd_data(’1’+pin)”. To save the add operation for every call, the entry “lcd_testpin(uint8_t pin)” was added to the lcd_routines.c.

The pseudo calls in the form “delay_ms(200)” are not implemented as library calls, but wait loops are implemented for every call. This will consume much memory, if you have many calls at different location in your program. All of this pseudo calls are replaced with calls to my special assembly written library, which uses only 74 bytes of flash memory (@8MHz), but enables calls from wait1us() to wait5s() in steps of 1,2,3,4,5,10,20... The routines include the Watch Dog Reset for all calls above 50ms. Every wait call usually only need one instruction (2 Byte). Wait calls with interim value such as 8ms need two calls (5ms and 3ms or two times a 4ms call). I don’t know any implementation, which is more economical if you use many wait calls in your program. The calls uses no registers, only the Stack Pointers for the return adresses in the RAM (at most 28 Byte stack space in current release) is used. The total list of functions is:

wait1us(), wait2us(), wait3us(), wait4us(), wait5us(), wait10us(),
wait20us(), wait30us(), wait30us(), wait40us(), wait50us(), wait100us(),
wait200us(), wait300us(), wait400us(), wait500us(), wait1ms(),
wait2ms(), wait3ms(), wait4ms(), wait5ms(), wait10ms(),
wait20ms(), wait30ms(), wait40ms(), wait50ms(), wait100ms(),
wait200ms(), wait300ms(), wait400ms, wait500ms(), wait1s(),
wait2s(), wait3s(), wait4s() and wait5s();

That are 36 functions with only 37 instructions inclusive Watch Dog Reset! There is really no way to shorten this library. Last not least matches the wait calls the exactly delay time, if the lowest wait call does. Only the wait calls above 50ms are one cycle per 100ms to long because of the additionally integrated watch dog reset.

Additionally the often used calling sequence “wait5ms(); ReadADC...();” is replaced by the call “W5msReadADC(...);”. The same is done for the sequence “wait20ms(); ReadADC(...);” which is replaced by one “W20msReadADC(...);” call. The function ReadADC is additionally written in assembly language, so that this add-on could be implemented very effective. The functional identical C-version of the ReadADC function is also available as source.
Chapter 9
To Do List and new ideas

1. Add more and better documentation.

2. Think about how we can get the real internal resistance of port B output (resistor switching port) instead of assuming, that ports are equal.

3. Can discharging of capacitors be made more quickly, if the minus pin is additionally raised with the 680Ω resistor to VCC (+)?

4. Check if the tester can use floating-point representation of values. The risk of overflow is lower. There is no need to use multiplication and division together to build a multiplication with a non integer factor. But I don’t know how much flash memory must be spend for the library.

5. Write User’s guide for configuring the tester with the Makefile options and description of the build chain.

6. If the holding current of a thyristor can not be reached with the 680Ω resistor, is it harmless to switch the cathode directly to GND and the anode directly to VCC for a very short time? The current could reach more than 100mA. Will the port be damaged? What is with the power supply (voltage regulator)?

7. Check the Port afterwards with self test function!

8. Idea for a New Projekt: USB version without LCD-Display, Power from USB, Communication to PC over a USB-Serial bridge.

9. Selectable separated 2-pin measurement for quicker selection of parts (resistors and capacitors).
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